# SiNeRF: Sinusoidal Neural Radiance Fields for Joint Pose Estimation and Scene Reconstruction\*

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### Overview



# **2** Brief introduction on paper

### • What can SiNeRF do?

SiNeRF is designed for improving the Joint Optimization (JO) [1], i.e. jointly learning camera poses and reconstructing scenes simultaneously.

### • Motivation?

JO is sensitive to scene contents and naively adopting a large network for radiance mapping does not always work. Thus, we believe there may exist a systematic sub-optimality in JO with multiple sources. We need non-trivial approaches to alleviate.

### • What we found?

**★ Radiance mapping network is not good enough.** Either increasing network size or adopting sinusoidal activations only improve performances on particular scenes. **★ Random ray sampling method is not good enough.** Random Sampling harms the performances on scenes with similar patterns. The pixels should not be treated equally. **★ Diversity matters for ray sampling.** Too-concentrated ray batch will lead to homogeneous rendering. Diversity is what we should learn from Random Sampling. In our work, we discovered and verified the sources for the sub-optimality of JO and then improved them with SiNeRF.

## References

# **3** Quantitative Results

		Mean Pose Error			
Tr	Translation(×10 <sup>-2</sup> ) $\downarrow$				
<i>NeRFmm12</i> 1.807	28 NeRF 1.	<i>mm256</i> SiN 994 1.	NeRF NeRFn   519 3.9	1 <i>m128 1</i> 64	
Table 1: Mea	an pose erro	r comparisons on	LLFF dataset. Pl	ease refer to	
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# **4 Qualitative Results**



Figure 2: Part of qualitative results on LLFF dataset. Please refer to the paper for full results.



Figure 3: Qualitative results of ablation study.

[1] Zirui Wang, Shangzhe Wu, Weidi Xie, Min Chen, and Victor Adrian Prisacariu. Nerf-: Neural radiance fields without known camera parameters. arXiv preprint arXiv:2102.07064, 2021.



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er to the paper for full results.