

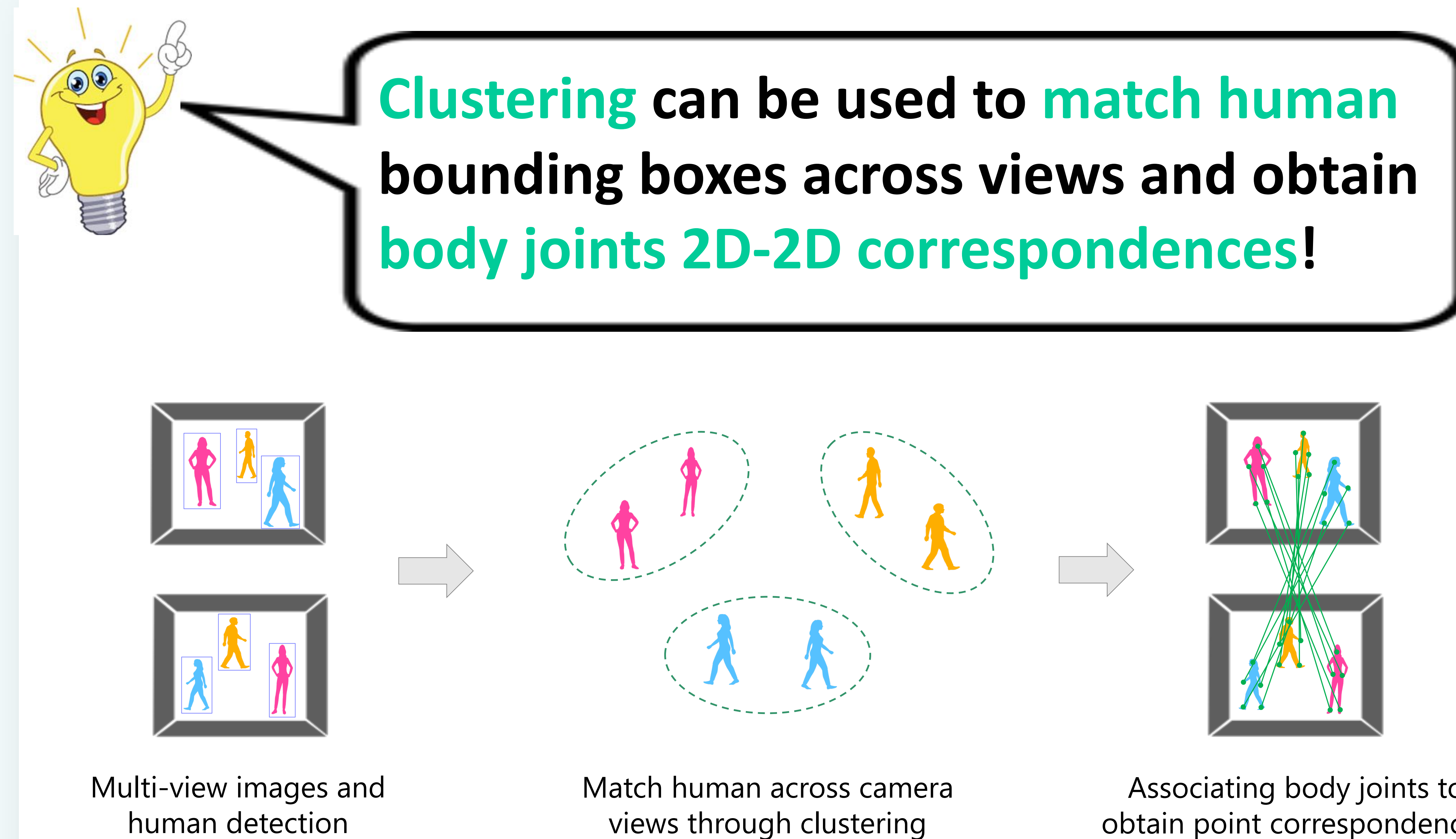
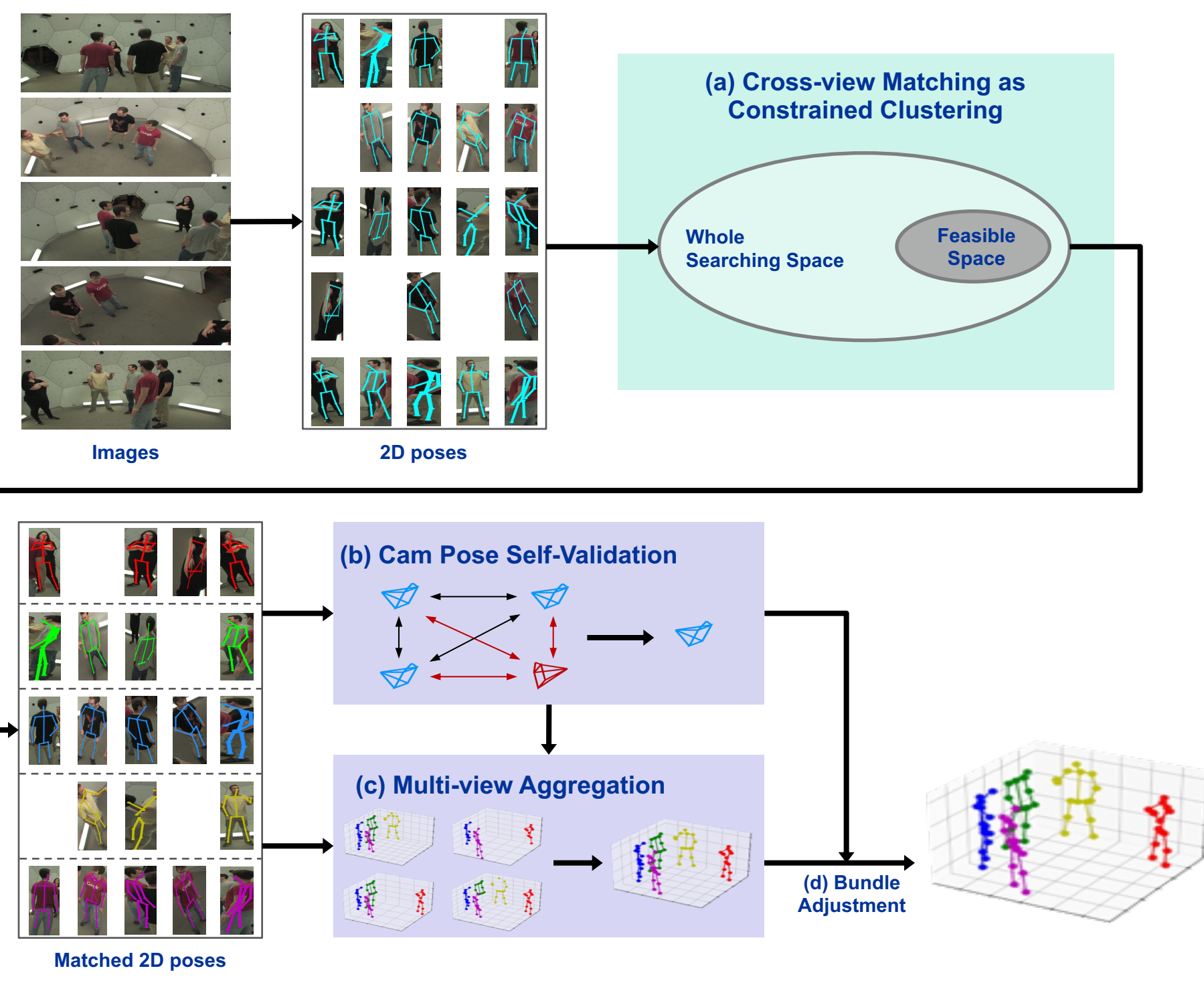
## Background

1. Multi-view multi-person 3D human pose estimation mostly done in controlled env
2. In many real-life scenarios, camera poses are not likely to be readily available
3. We targets uncalibrated cam networks

## Method

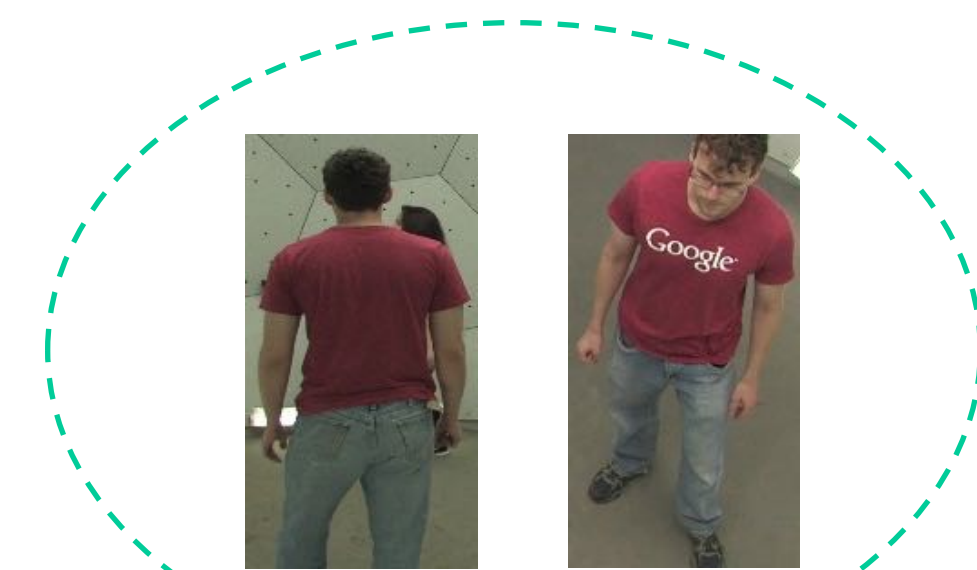
Our method includes three steps:

1. Match human boxes through clustering
2. Associate body joints for point corresponds
3. Solve cam and human pose



## Cross-view matching constraints

- **Constraint 1:** Cluster size larger than 2



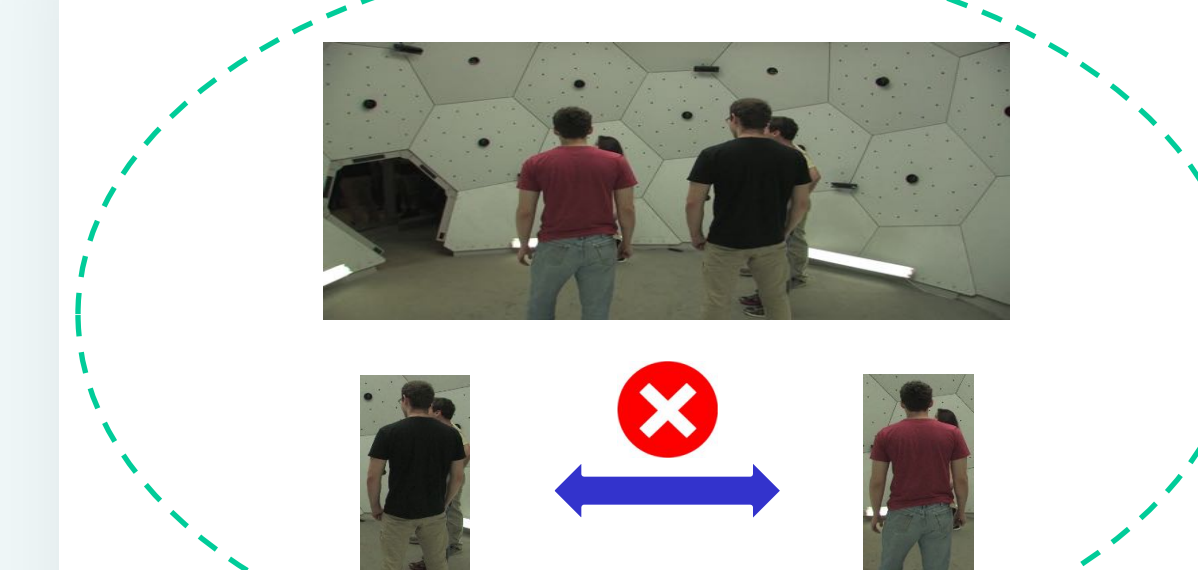
At least two cameras for solving depth ambiguity

- **Constraint 2:** Cluster size smaller than number of cams



At most observed by N cameras

- **Constraint 3:** Ppl from same camera not in the same cluster



Observations from the same cam must be different ppl

## Result

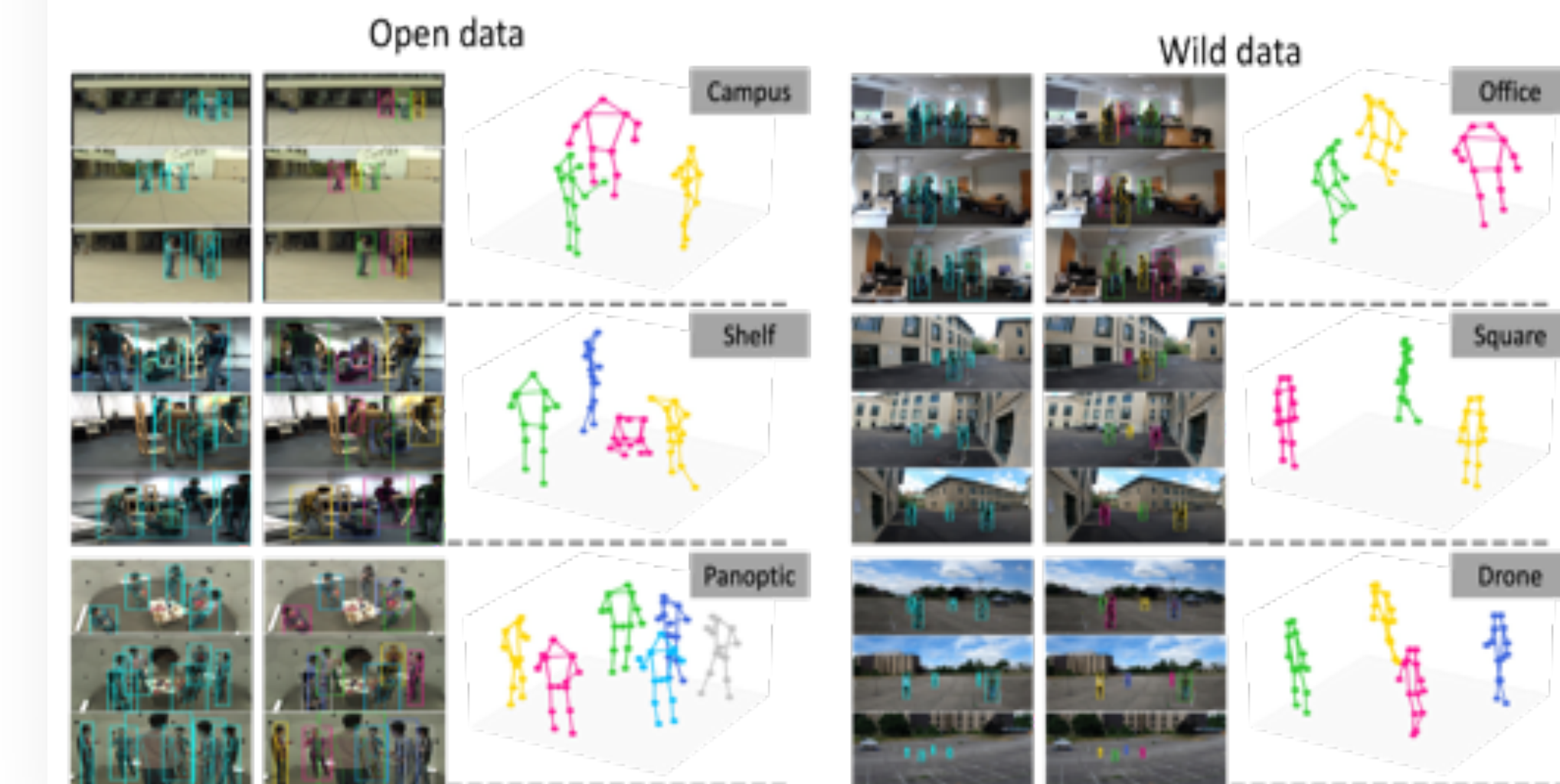
- Reaches SOTA performance **without requiring camera poses, 3D data, or network training**

Campus	CamPose	Training	Actor 1	Actor 2	Actor 3	Average
Huang <i>et al.</i> [22]	✓	✓	98.0	94.8	97.4	96.7
Tu <i>et al.</i> [55]	✓	✓	97.6	93.8	98.8	96.7
Zhang <i>et al.</i> [63]	✓	✓	98.2	94.1	97.4	96.6
Reddy <i>et al.</i> [48]	✓	✓	97.9	95.2	99.1	97.4
Belagiannis <i>et al.</i> [4]	✓	-	93.5	75.7	84.4	84.5
Ershadi <i>et al.</i> [15]	✓	-	94.2	92.9	84.6	90.6
Dong <i>et al.</i> [13]	✓	-	97.6	93.3	98.0	96.3
Perez-Yus <i>et al.</i> [46]	✓	-	98.4	93.4	98.3	96.7
Ours	-	-	99.0	94.7	99.6	97.8

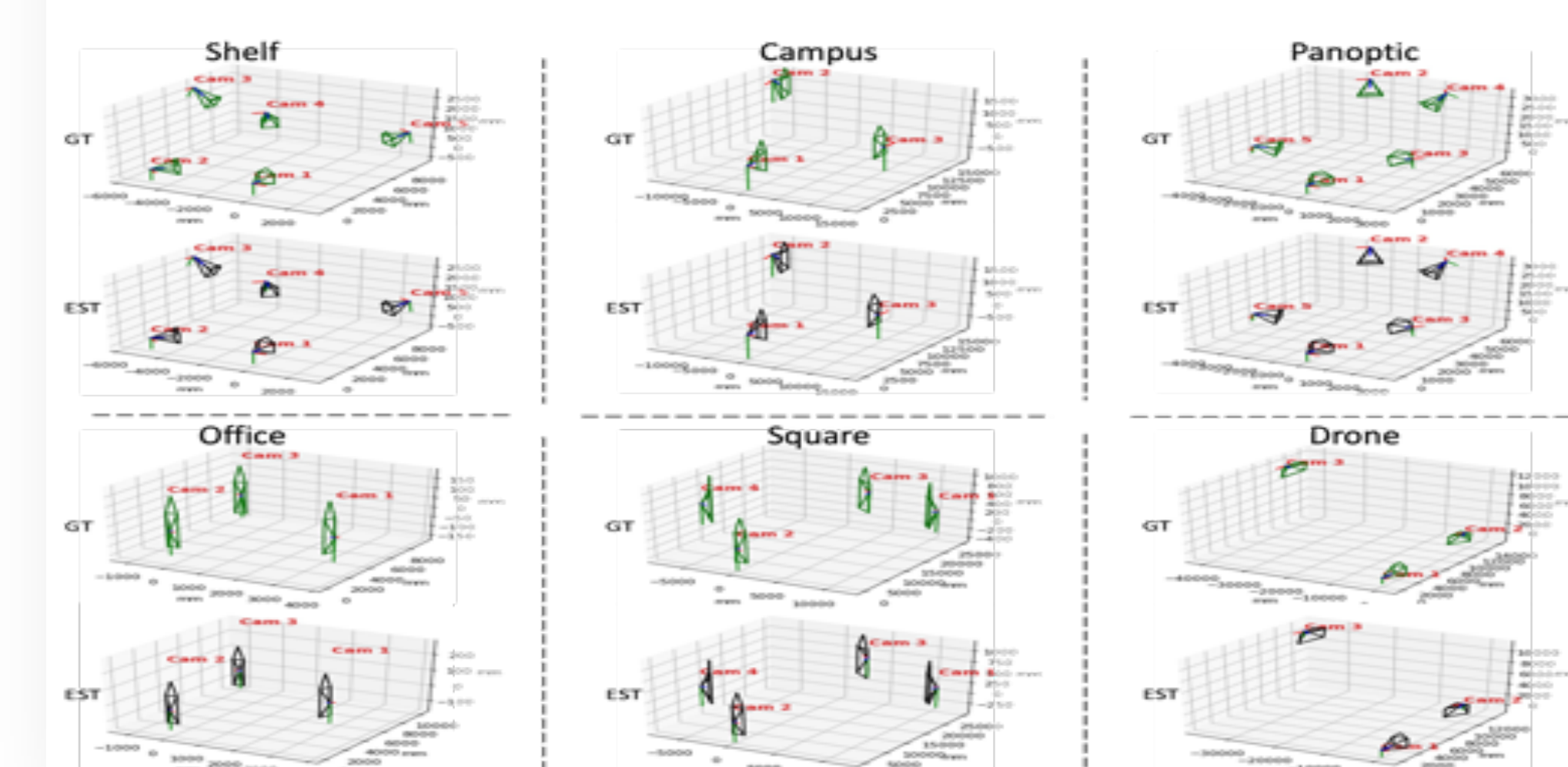
  

Shelf	CamPose	Training	Actor 1	Actor 2	Actor 3	Average
Huang <i>et al.</i> [22]	✓	✓	98.8	96.2	97.2	97.4
Tu <i>et al.</i> [55]	✓	✓	99.3	94.1	97.6	97.0
Zhang <i>et al.</i> [63]	✓	✓	99.3	95.1	97.8	97.4
Reddy <i>et al.</i> [48]	✓	✓	99.1	96.3	98.3	98.2
Wu <i>et al.</i> [58]	✓	✓	99.3	96.5	97.3	97.7
Belagiannis <i>et al.</i> [4]	✓	-	75.3	69.7	87.6	77.5
Ershadi <i>et al.</i> [15]	✓	-	93.3	75.9	94.8	88.0
Dong <i>et al.</i> [13]	✓	-	98.8	94.1	97.8	96.9
Perez-Yus <i>et al.</i> [46]	✓	-	98.9	92.3	97.8	96.5
Ours	-	-	99.6	95.2	98.5	97.8

- Generalizes well to the **in-the-wild** data



- Can estimate cam poses **across various settings**



You are welcome to refer to our paper or reach out to the author (QR) for details.  
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