

# Semi-supervised Object Detection with Object-wise Contrastive learning and regression uncertainty



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## 1. Introduction

### Semi-Supervised Object Detection

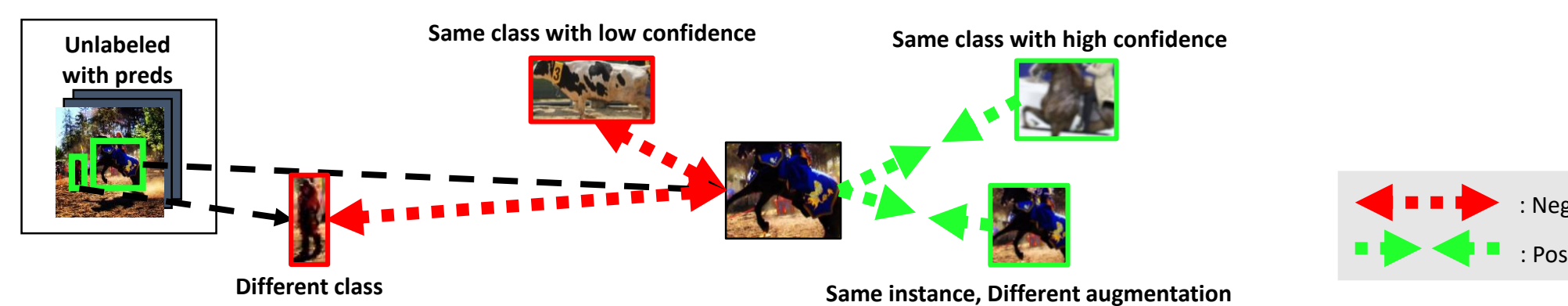
- Aims to boost detection performance by leveraging **extra unlabeled data**
- Since the **pseudo-labels are noisy**, pseudo-label filtering is crucial

### Previous Works & Limitations

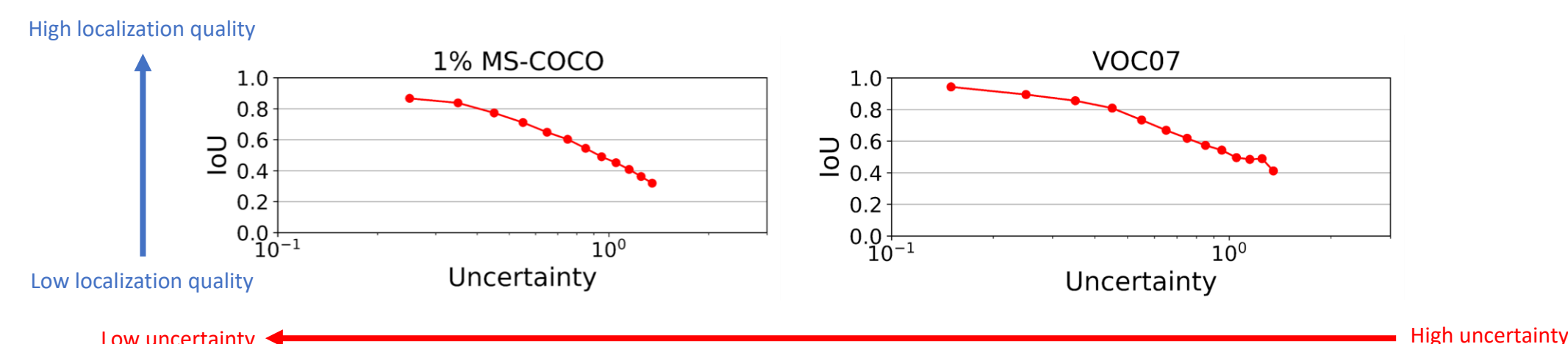
- **Teacher-Student Framework** [1]
  - Teacher network generates pseudo-labels for unlabeled data to assist the training of a student network
- **Previous Works ...**
  - Adopted classification score to select pseudo-labels with confidence higher than a pre-defined threshold
  - Heuristic designs to measure the localization quality
- **Existing classification scores and localization optimization is suboptimal**
  - Lack of labeled data makes classification scores less discriminative,
  - Measurement of pseudo-labels' localization quality is less investigated

### Key Ideas

- **Object-wise Contrastive Learning (OCL)** enhances the discriminativeness of the classification score

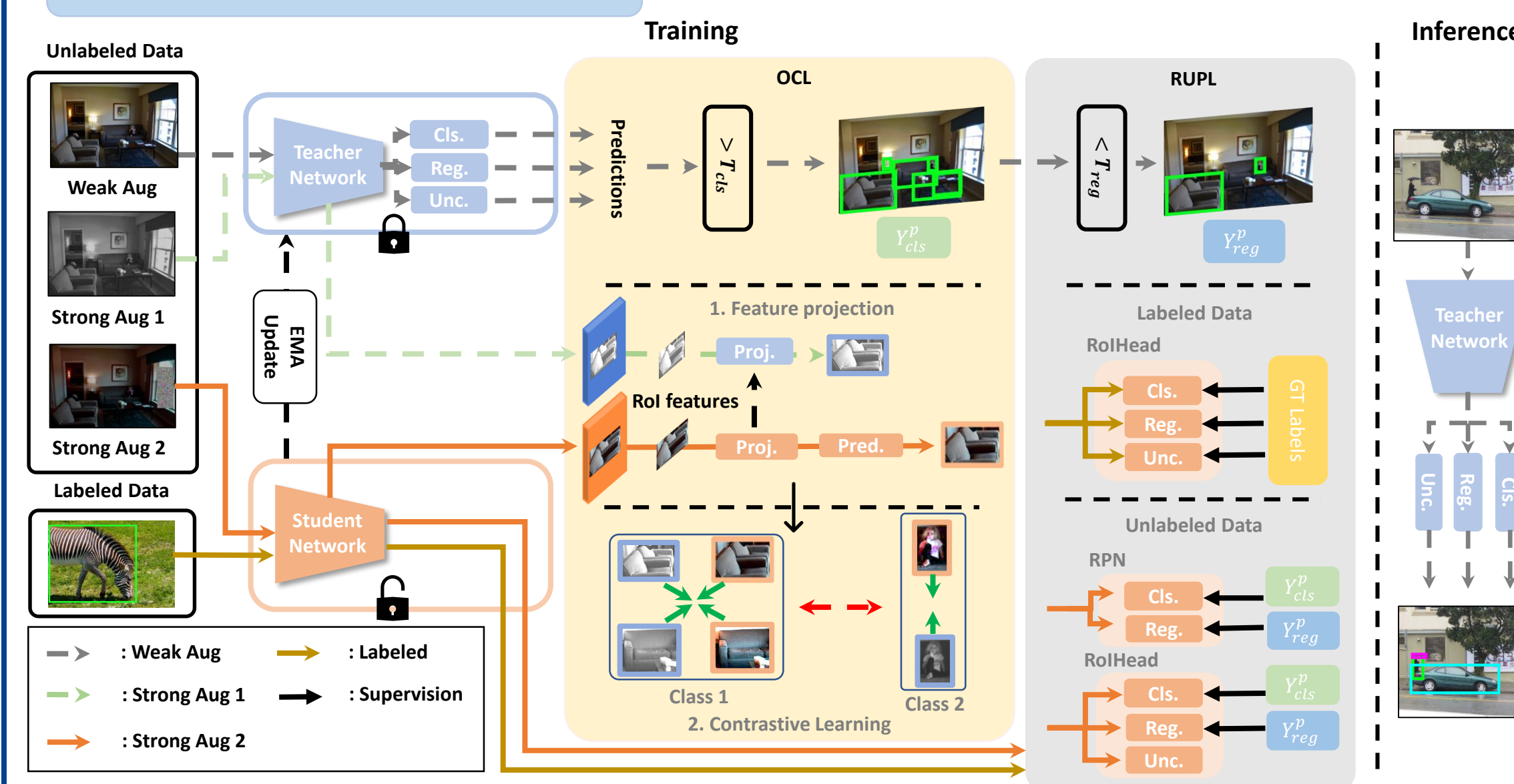


- **Regression-Uncertainty-guided Pseudo-Labeling (RUPL)** models aleatoric uncertainty of object localization for label filtering



## 2. Proposed Method

### Framework Overview

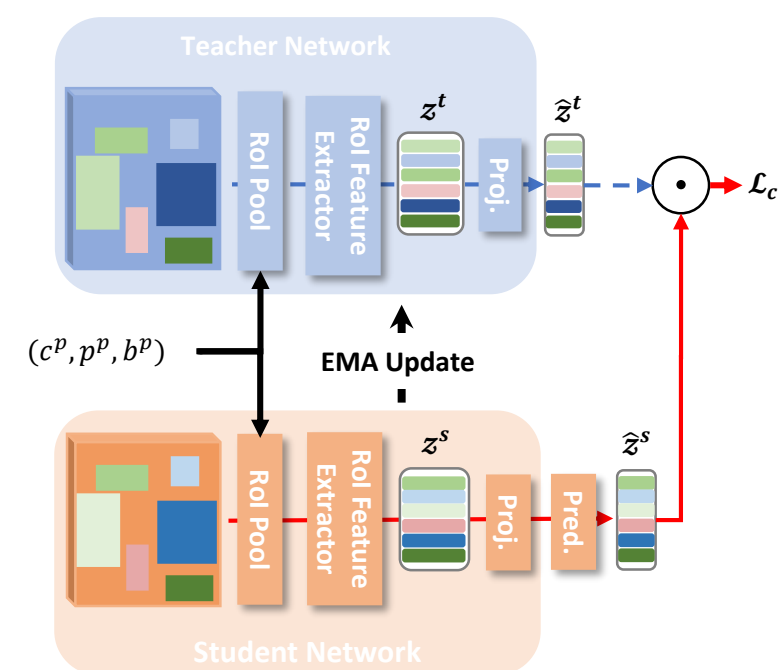


### Object-wise Contrastive Learning (OCL)

- **Object-wise Contrastive Loss**

$$\mathcal{L}_{cont} = -\frac{1}{N_o} \sum_{n=1}^{N_o} \frac{1}{\sum_{m=1}^{N_o} \mathbb{1}(w_{nm} > 0)} \sum_{m=1}^{N_o} w_{nm} \log \frac{\exp(\hat{z}_n^S \cdot \hat{z}_m^T / \tau)}{\sum_l \mathbb{1}(l \neq n) \exp(\hat{z}_n^S \cdot \hat{z}_l^T / \tau)}$$

$$w_{nm} = \begin{cases} 1 & \text{if } n = m \\ p_n^p \cdot p_m^p & \text{if } \begin{cases} n \neq m \\ c_n^p = c_m^p \\ p_n^p, p_m^p > T_{cont} \end{cases} \\ 0 & \text{otherwise.} \end{cases}$$



- **Pseudo-label for Classification**

$$\{X_{cls}^p, Y_{cls}^p\} = \{(x_i^p, y_i^p) | p_i^p > T_{cls}\}_{i=1}^{N_u}$$

### Regression-Uncertainty-guided Pseudo-labeling (RUPL)

- **Uncertainty-aware Regression Loss** [2]

$$\mathcal{L}_{roi,reg} = \frac{\text{smoothL}_1(\hat{t}, t)}{\sigma^2} + \lambda_{unc} \log(\sigma^2)$$

- **Pseudo-label for Regression**

$$\{X_{reg}^p, Y_{reg}^p\} = \{(x_i^p, y_i^p) | p_i^p > T_{cls} \text{ and } \hat{\sigma}_{i^p}^2 < T_{reg}\}_{i=1}^{N_u}$$

## 3. Experiments

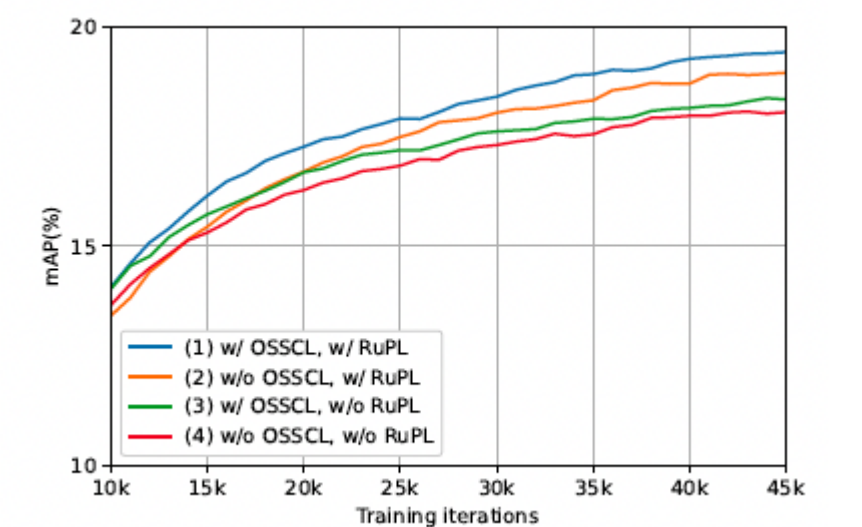
### Main Results

Methods	VOC	VOC + coco20cls
Baseline [2]	48.69	50.34
Ours	<b>52.04</b>	<b>53.88</b>

Methods	COCO 1%	COCO 5%	COCO 10%	Additional	coco-35k
Baseline [2]	20.75	28.27	31.50	41.30	36.36
Ours	<b>21.63</b>	<b>30.66</b>	<b>33.53</b>	<b>41.89</b>	<b>37.13</b>

### Ablation Study

	OCL	RUPL	AP <sub>50:95</sub>	AP <sub>50</sub>	AP <sub>75</sub>
(1)	✓	✓	<b>19.42</b>	34.65	<b>19.36</b>
(2)		✓	18.95	33.82	19.07
(3)	✓		18.34	<b>35.21</b>	17.16
(4)			18.05	34.45	17.09



Method	AP <sub>50:95</sub>
Box jittering [4]	18.15
Predicted IoU [5]	18.85
Aleatoric uncertainty [3] (Ours)	<b>18.95</b>

Method	AP <sub>50:95</sub>
w/o CL	18.05
Self-sup CL	18.24
OCL (Ours)	<b>18.34</b>

## 4. Conclusion

- Propose a two-step pseudo-label filtering for SSOD
- Deal with both classification and regression heads
- OCL enhances discriminativeness of classification score
- RUPL learns regression uncertainty to measure the localization quality
- Achieve remarkable performance gain against our baseline and show competitive results compared to other SOTA

### References

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- [3] A. Kendall, *et al.* What uncertainties do we need in bayesian deep learning for computer vision? In NIPS, 2017.
- [4] M. Xu, *et al.* End-to-end semi-supervised object detection with soft teacher. In ICCV, 2021.
- [5] H. Wang, *et al.* 3dioumatch: Leveraging iou prediction for semi-supervised 3d object detection. In CVPR, 2021.