

A Experiment on CIFAR100

We have run additional experiments on CIFAR100 following the setup in DeiT [1] but w/o pretraining on ImageNet1K.

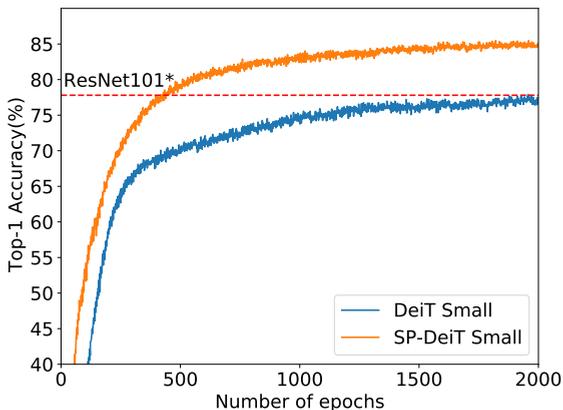
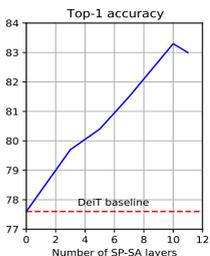
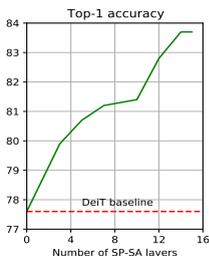


Figure 1: Training SP-ViT (DeiT [1] as baseline) on CIFAR100.

B Numbers of Substituted SA Layers



(a) 12 layer SP-ViT



(b) 16 layer SP-ViT

Figure 2: Accuracy(%) of SP-ViT on ImageNet-100 with different numbers of SP-SA layers. Fig. 2a and Fig. 2b show consistent improvements of our SP-ViT over DeiT Baselines with a total number of 12 and 16 layers respectively.

We first investigate how the model performance is affected by the number of SP-SA layers. The layers are substituted from bottom to top and a classification token is inserted after the last SP-SA layer. It is shown in Fig. 2a that substituting a number of SA layers with SP-SA results in improved accuracy comparing to DeiT baseline (0 layer). In general, the performance improves as more layers are substituted. For a model with 12 layers, the best performance is achieved when 10 layers are substituted. When substituting all but the last SA layer with SP-SA, the performance drops slightly. We hypothesize that when the classification token is only involved in the last layer, the class-specific features are not adequately

| Sub. layers | Cls token insertion layers | Top-1 (%) |
|-------------|----------------------------|-------------|
| 0 | 0 | 77.6 |
| 0 | 10 | 81.7 |
| 10 | 10 | 83.3 |
| 0 | Global Average Pooling | 79.5 |
| 12 | Global Average Pooling | 81.7 |

Table 1: Eliminate the effect of inserting the class token at later layers on ImageNet-100.

extracted. We further investigated a deeper model in Fig. 2b, and found the similar trend. The best performance is achieved when the first to the penultimate layer are substituted. As discussed in the main text, we add the classification token directly after SP-SA layers because it has no valid 2D relative coordinate. To exclude the influence of inserting it at deeper layers instead of the first, we conduct a further comparison in Tab. 1.

C More Experiment Details

We show in Tab. 2 the default hyperparameters for training our SP-ViT on ImageNet-1K based on DeiT and LV-ViT respectively. All hyperparameter settings follow the baselines' except that for DeiT-based SP-ViTs we adopt a smaller learning rate.

| Base Config. | DeiT | LV-ViT |
|----------------------------|--|--|
| Supervision | Standard | Token labeling |
| SP-SA layers | 10 | 10 |
| Epoch | 300 | 300 |
| Optimizer | AdamW | AdamW |
| Batch size | 1024 | 1024 |
| LR | $2.5e - 4 \cdot \frac{\text{batch size}}{512}$ | $1e - 3 \cdot \frac{\text{batch size}}{640}$ |
| LR decay | cosine | cosine |
| Weight decay | 0.05 | 0.05 |
| Warmup epochs | 5 | 5 |
| Label smoothing ϵ | 0.1 | 0.1 |
| Stoch. Depth | 0.1 | 0.1 |
| Repeated Aug | ✓ | - |
| RandAug | 9/0.5 | 9/0.5 |
| Mixup prob. | 0.8 | - |
| Erasing prob. | 0.25 | 0.25 |

Table 2: Default hyperparameters for our SP-ViTs on ImageNet-1K.

For our SP-ViT trained on ImageNet-1K, we further adopt the Conditional Positional Encoding (CPE) [10], which is found to be effective as shown in Tab. 3.

| Model | CPE [▣] | Top-1 (%) |
|----------|---------|-----------|
| SP-ViT-S | - | 83.7 |
| | ✓ | 83.9 |
| SP-ViT-M | - | 84.7 |
| | ✓ | 84.9 |
| SP-ViT-L | - | 85.3 |
| | ✓ | 85.5 |

Table 3: Effect of Conditional Positional Encoding [▣] on ImageNet-1K.

D Python Implementation

We also list our Pytorch implementation of SP-SA List. 1 SP-SA can be easily integrated into any existing vision transformer models by directly replacing a number of SA layers. Calculating the relative coordinates to query patches is trivial, so this part of code is not included for simplicity. Note that the insertion of classification token should be moved after SP-SA layers, as mentioned in the main text.

E More Visualization

We provide more examples of learned Spatial Priors (SP) by our SP-ViT based on DeiT-Small and trained on ImageNet-1K in Fig. 3 and Fig. 4.

References

- [1] Xiangxiang Chu, Zhi Tian, Bo Zhang, Xinlong Wang, Xiaolin Wei, Huaxia Xia, and Chunhua Shen. Conditional positional encodings for vision transformers. *arXiv preprint arXiv:2102.10882*, 2021.
- [2] Hugo Touvron, Matthieu Cord, Douze Matthijs, Francisco Massa, Alexandre Sablayrolles, and Herve Jegou. Training data-efficient image transformers & distillation through attention. In *ICML 2021: 38th International Conference on Machine Learning*, 2021.

Listing 1 SP-SA SP-SA.py

```
1 import torch 138
2 from torch import nn 139
3 140
4 class SP_SA(nn.Module): 143
5     def __init__(self, dim, num_heads=8, qk_scale=None, attn_drop=0., 144
6         proj_drop=0., rel_indices=None, **kwargs): 145
7         super().__init__() 146
8         self.num_heads = num_heads 147
9         self.dim = dim 148
10        head_dim = dim // num_heads 149
11        self.scale = qk_scale or head_dim ** -0.5 150
12        self.v = nn.Linear(dim, dim, bias=False) 151
13        self.qk = nn.Linear(dim, dim * 2, bias=False) 152
14        self.w1 = nn.Linear(2, dim, bias=True) 153
15        self.w2 = nn.Parameter(torch.zeros(dim, 1)) 154
16        self.b2 = nn.Parameter(torch.ones(num_heads)) 155
17
18        self.attn_drop = nn.Dropout(attn_drop) 156
19        self.proj = nn.Linear(dim, dim) 157
20        self.proj_drop = nn.Dropout(proj_drop) 158
21        self.act = nn.ReLU() 159
22        self.rel_indices = rel_indices 160
23
24    def forward(self, x): 161
25        B, N, C = x.shape 162
26        attn = self.get_attention(x) 163
27
28        v = self.v(x).reshape(B, N, self.num_heads, C // self.num_heads). 164
29            permute(0, 2, 1, 3) 165
30        x = (attn @ v).transpose(1, 2).reshape(B, N, C) 166
31        x = self.proj(x) 167
32        x = self.proj_drop(x) 168
33        return x 169
34
35    def get_attention(self, x): 170
36        B, N, C = x.shape 171
37
38        # Calculating Patch Score 172
39        qk = self.qk(x).reshape(B, N, 2, self.num_heads, C // self. 173
40            num_heads).permute(2, 0, 3, 1, 4) 174
41        q, k = qk[0], qk[1] 175
42        patch_score = (q @ k.transpose(-2, -1)) * self.scale 176
43
44        # Calculating Spatial Prior 177
45        sp_hidden = self.w1(self.rel_indices).view(1, N, N, self. 178
46            num_heads, self.dim // self.num_heads) 179
47        sp = torch.einsum('nm,hijm->hijn', (self.w2.view(self.num_heads, 180
48            -1), self.act(sp_hidden))) + self.b2 181
49        sp = sp.repeat(B, 1, 1, 1) 182
50
51        enhanced_attention = (patch_score * sp.permute(0, 3, 1, 2)). 183
52            softmax(dim=-1) 184
53        attn = self.attn_drop(enhanced_attention) 185
54        return attn 186
```

184
185
186
187
188
189
190
191
192
193
194
195
196
197
198
199
200
201
202
203
204
205
206
207
208
209
210
211
212
213
214
215
216
217
218
219
220
221
222
223
224
225
226
227
228
229

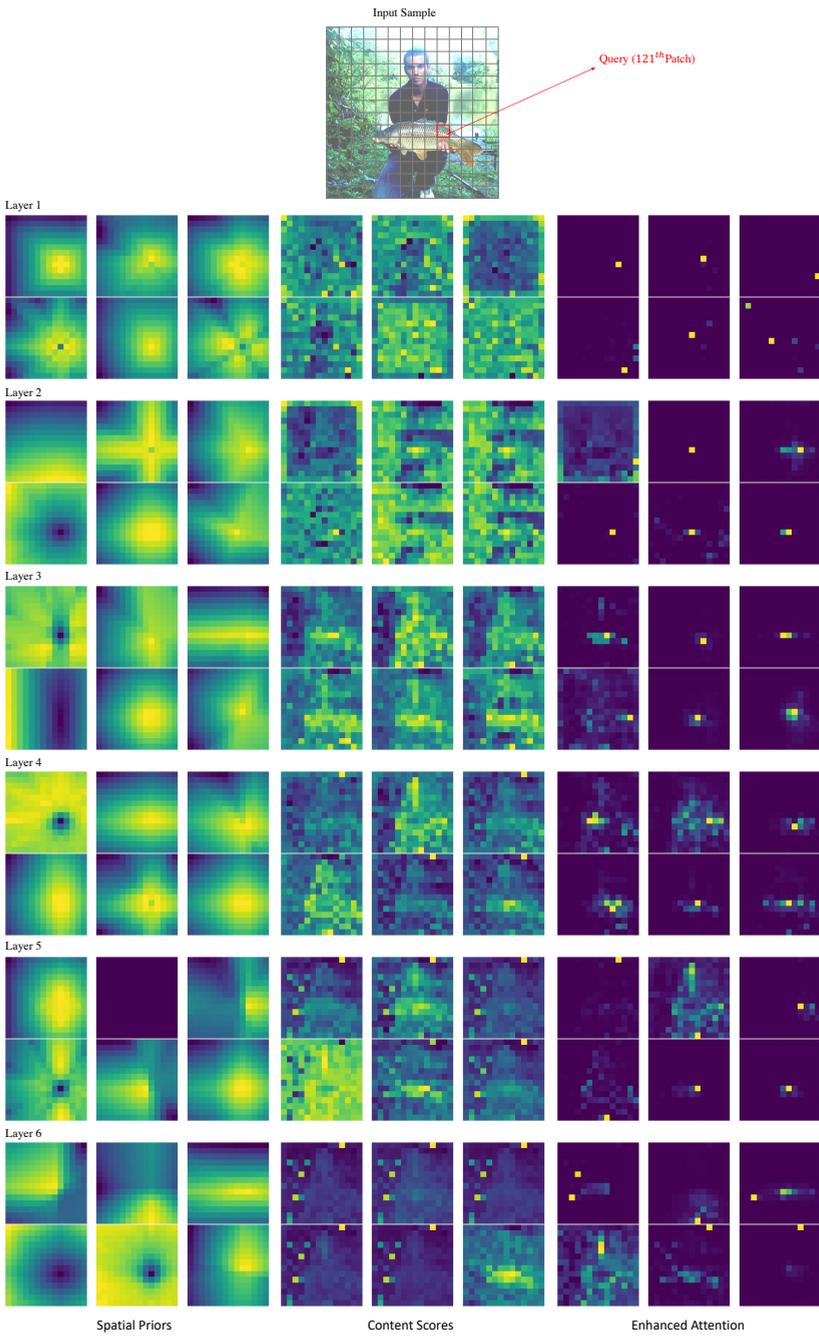


Figure 3: More Visualization of the learned 2D SPs, content scores and the enhanced attention of layer 1-6 for the 121th query patch.

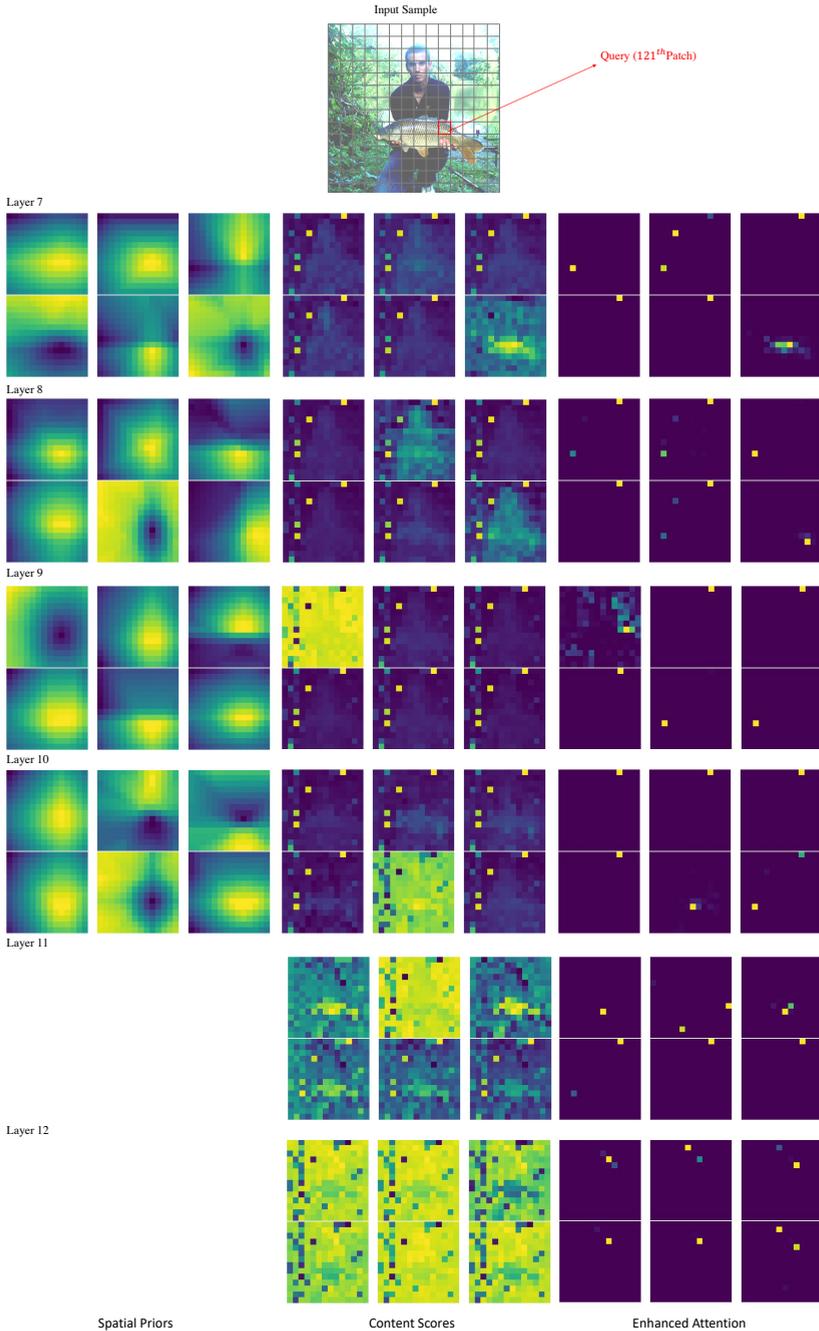


Figure 4: More Visualization of the learned 2D SPs, content scores and the enhanced attention of layer 7-12 for the 121th query patch. Note that layer 11 and 12 are vanilla SA layers, thus no spatial priors are existed.

230
231
232
233
234
235
236
237
238
239
240
241
242
243
244
245
246
247
248
249
250
251
252
253
254
255
256
257
258
259
260
261
262
263
264
265
266
267
268
269
270
271
272
273
274
275