

DA-CIL: Towards Domain Adaptive Class-Incremental 3D Object Detection

Paper ID: 916

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Introduction

Background

Deep learning-based 3D object detection has received considerable attention in 3D point clouds.

Challenges

Catastrophic Forgetting: The performance of DL models on old classes tends to decrease substantially when trained on novel classes.

Domain Shift: DL models trained on one domain (i.e., source domain) always suffer tremendous performance degradation when evaluated on another domain (i.e., target domain).

We identify a new CIL scenario where domain shift occurs when adapting new classes across domains and formulate a new CIL paradigm to enable domain adaptive class-incremental learning for 3D object detection.

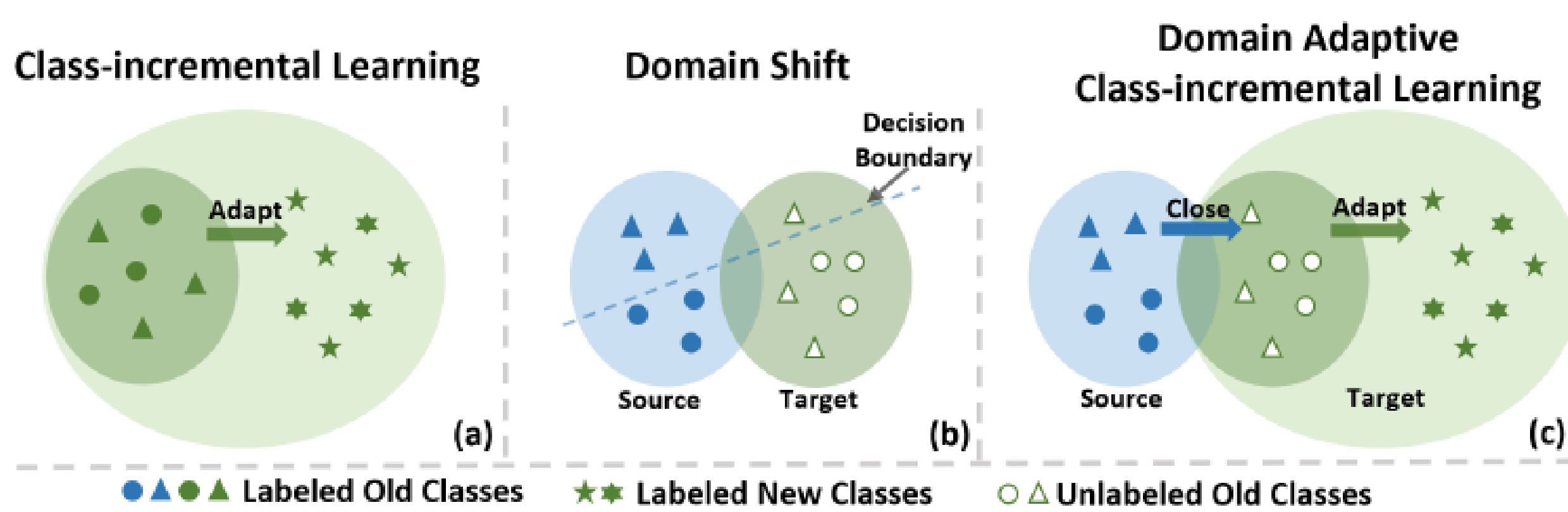
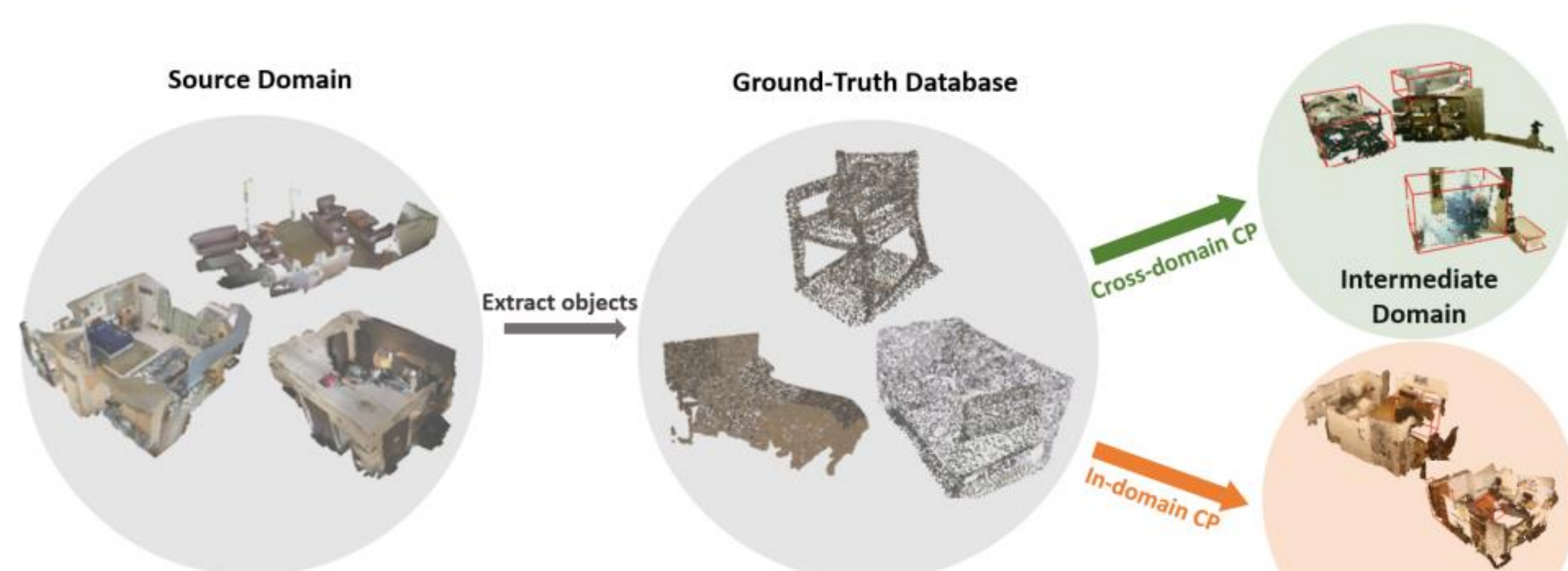


Figure 2: The difference between CIL and DA-CIL. (a) CIL is designed for adapting new classes without forgetting old classes in the same domain. (b) Domain shift always exists between source and target domains. (c) DA-CIL is designed to close the domain shift and adapt new classes across different domains.

Method

Dual-Domain Copy-Paste Augmentation

- To relieve data scarcity and reduce the domain gap at the data level, we extensively leverage copy-paste (CP) augmentation techniques for creating cross-domain and in-domain point clouds.



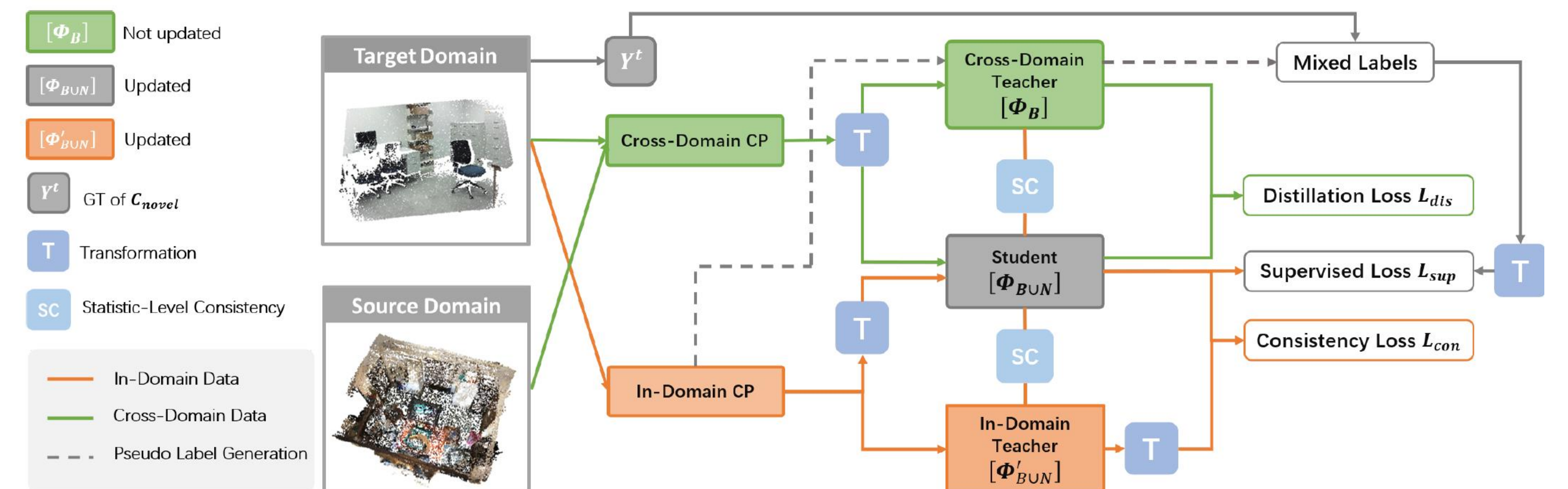
Multi-Level Consistency

- To facilitate the dual-teacher knowledge transfer, we propose multi-level consistency regularization from two aspects.
 - Statistics-Level (SC) Consistency (Batch Normalization parameters alignment)
 - Bounding Box-Level Consistency (center-, class-, and size-level consistency loss)

$$L_{center} = dist(Pair_N) + dist(Pair_M),$$

$$L_{class} = \frac{1}{M} \sum_{i=1}^M D_{KL}(p_s^i, p_d^j), \quad (b_s^i, b_d^j) \in Pair_M,$$

$$L_{size} = \frac{1}{M} \sum_{i=1}^M MSE(s_s^i, s_d^j),$$



Dual-Teacher Training

- Cross-domain Teacher:** The student model learns the underlying knowledge in base classes from a cross-domain teacher via distillation loss (square of Euclidean distance between the classification logits of different bounding boxes).
- In-domain Teacher:** Meanwhile, the EMA in-domain teacher helps student model capture structure and semantic invariant information in objects with consistency loss.

$$L_{con} = L_{center} + \lambda_{class} L_{class} + \lambda_{size} L_{size},$$

- The mixed labels (pseudo base + real novel) are transformed by the same augmentation step that is applied on the augmented source domain to compute a supervised loss with the backbone VoteNet.

$$L = \lambda_{sup} L_{sup} + \lambda_{dis} L_{dis} + \lambda_{con} L_{con},$$

Experimental Results

Dataset

- ScanNet and SUN RGB-D.** We set 5 categories (bathtub, bed, bookshelf, chair, desk) as base classes and 5 additional categories (dresser, nightstand, sofa, table, toilet) in SUN RGB-D as novel classes in the target domain.

Quantitative Results

Table 1: 3D object detection performance mAP@0.25 on the SUN RGB-D validation set.

	Method	C_s^b	C_t^b	C_t^c	Base	Novel	All
Class-Incremental Learning (CIL)	Base train	✓	×	×	26.60	-	-
	Base train	×	✓	×	57.63	-	-
	Freeze-and-add	×	✓	✓	54.24	10.61	32.42
	Fine-tune	×	✓	✓	3.48	54.10	28.79
	MT [10]	×	✓	✓	49.63	61.21	55.42
	SDCoT [10]	×	✓	✓	52.04	59.48	55.76
	Ours	×	✓	✓	53.81	59.50	56.66
CIL under Domain Shift	Freeze-and-add	✓	×	✓	23.31	2.04	12.68
	Fine-tune	✓	×	✓	1.73	58.24	29.99
	MT [10]	✓	×	✓	33.84	59.03	46.43
	SDCoT [10]	✓	×	✓	29.41	57.74	43.57
	Ours	✓	×	✓	36.41	58.80	47.60
Base & Novel	Joint train	✓	×	✓	6.80	52.52	29.66
	Joint train	×	✓	✓	58.11	59.27	58.69

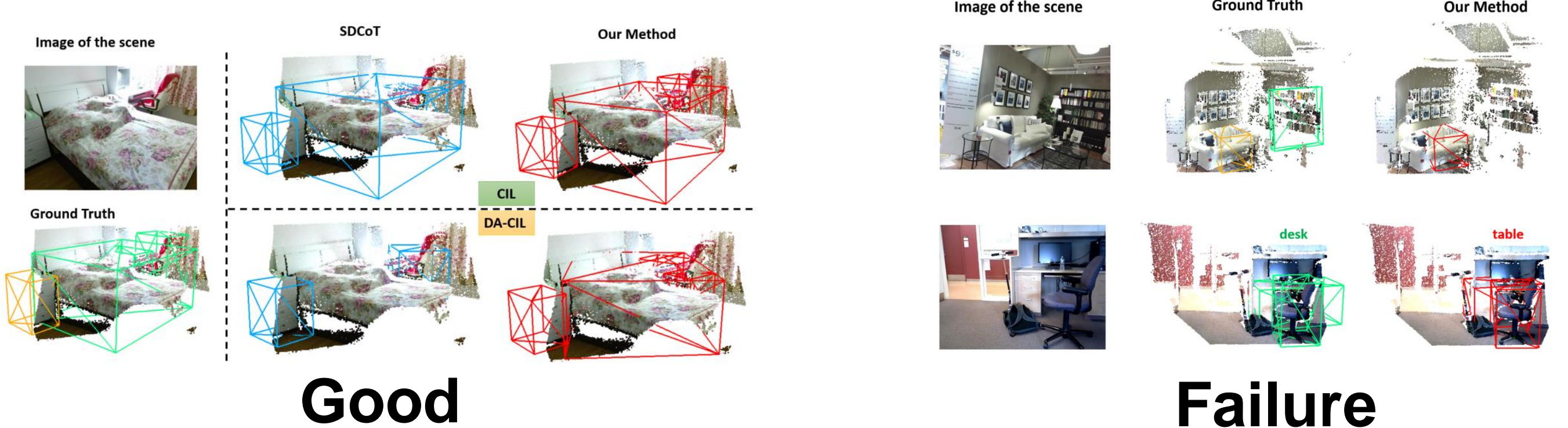
Table 3: Object detection performance mAP@0.25 of different augmentation techniques.

Method	Base	Novel	All
Mix3D [10]	33.48	57.89	45.69
CutMix [10]	31.71	57.15	44.43
Ours	36.41	58.80	47.60

Table 4: Object detection performance mAP@0.25 with exclusion of components in our method.

Method	Base	Novel	All
No cross-domain CP	33.67	59.95	46.81
No in-domain CP	35.70	58.39	47.05
No BN consistency	36.52	57.20	46.86
Ours	36.41	58.80	47.60

Qualitative Results



Acknowledgment

This research is supported by the Agency for Science, Technology and Research (A*STAR) under its AI3 HTP0 Seed Fund no. C211118008.

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