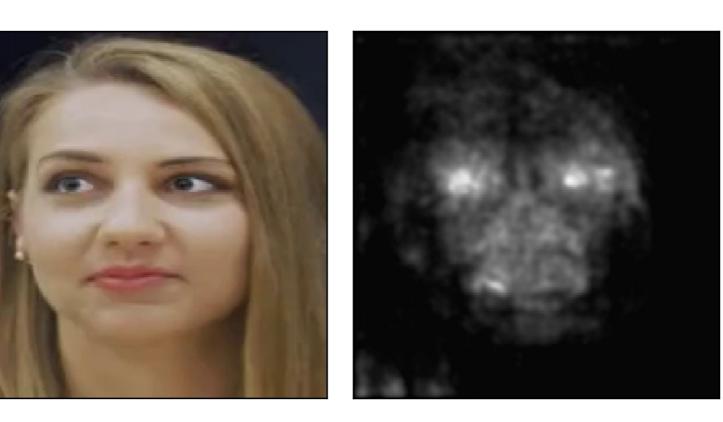
# **Quantitative Metrics for Evaluating Explanations of Video DeepFake Detectors**

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# Introduction

- DeepFake generation and detection are booming.
- explainability • However, is often left behind.



• Existing explanation metrics measure faithfulness and correctness with respect to the model but **ignore the user perspective**, which is

# **Evaluation**

#### **Overview of existing techniques**

Input preprocessing Gaussian filtering to remove high-frequency artifacts.

#### Data augmentation

#### Activation regularization **Total Variation loss to induce** smooth neuron activations.

Architecture design

left to subjective qualitative evaluation.

- We introduce quantitative metrics for evaluating explanations from the human perspective, both visual quality and informativeness.
- Using these metrics, we **compare existing approaches** to improve explanation heatmaps and discuss their effectiveness.

# **Proposed metrics**

Visual quality

How interpretable is the explanation heatmap to humans?

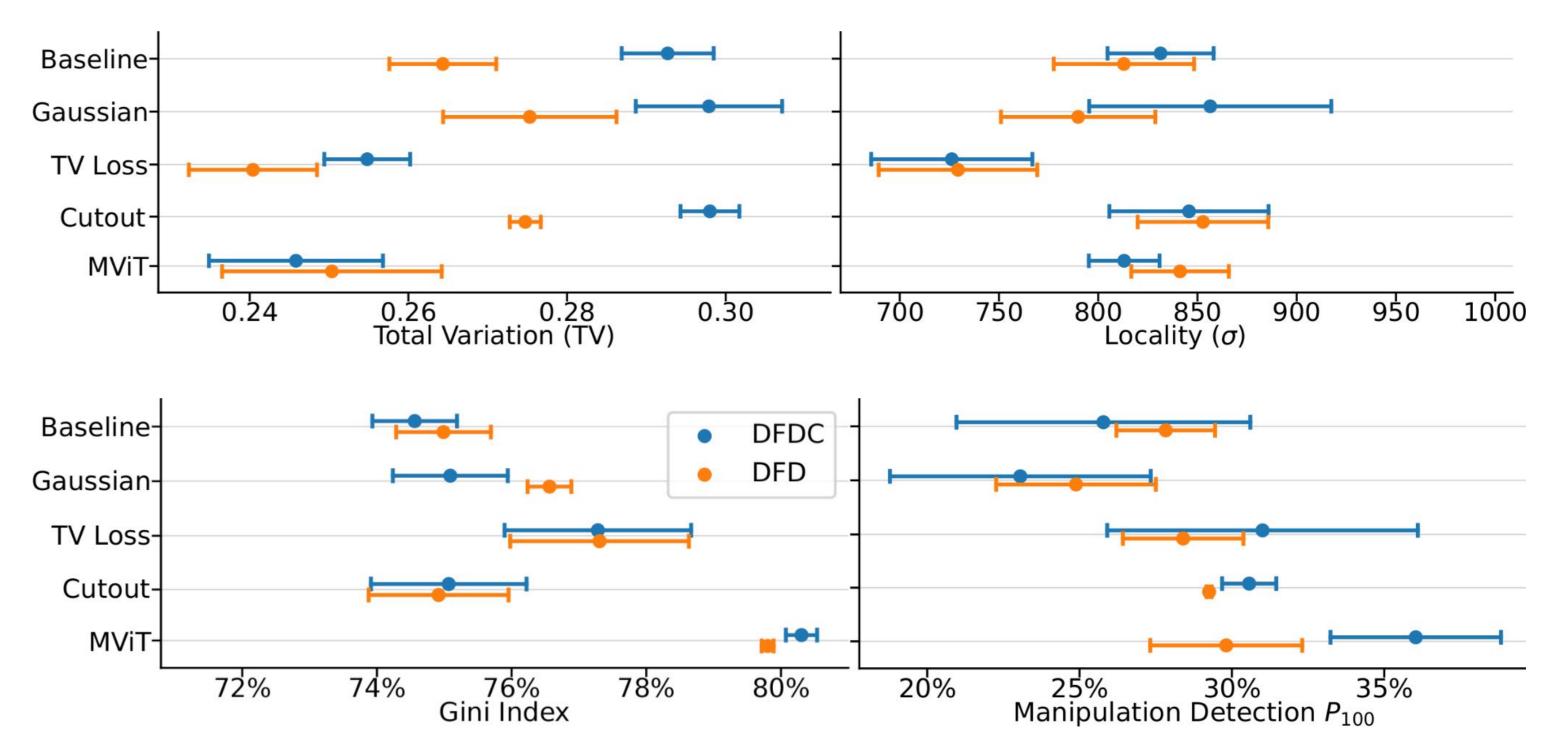
#### *Smoothness*

High-frequency cues, e.g. texture imperfections, are harder to perceive. An explanation h with low Total Variation appears smoother (low-freq).

$$\mathrm{TV}(h) = \int_{\mathcal{G}} \|\nabla h\|_1 \, d\lambda$$

Cutout augmentation to capture more diverse manipulation cues. Different inductive biases in CNN and transformers.

#### Let's evaluate them using our metrics



#### **Observations**

• Low-pass filtering the input videos does not improve explanation smoothness, contrary to what observed for images in previous work. • **Regularizing activations** yields smoother (low TV) and sparser (high Gini Index) explanations, but hinders classification accuracy.

#### **Spatial locality**

Explanations that focus on many spatially-distant details are ambiguous. We express the locality of an explanation through its spatial covariance.

$$\sigma = \left|\det(\mathbf{\Sigma})\right| = \left|\det\left(\mathbb{E}_h[\rho\rho^T] - \mathbb{E}_h[\rho]\mathbb{E}_h[\rho]^T\right)\right|$$

#### Sparsity

A few highly important regions are more informative than many mildly important ones. The Gini Index is used to measure such sparsity:

$$\operatorname{Gini}(h) = \frac{2}{THW} \frac{\sum_{i} i \cdot h(\rho_i)}{\sum_{i} h(\rho_i)} - \frac{THW + 1}{THW}$$

## Manipulation detection

Does the explanation focus on the forged parts?

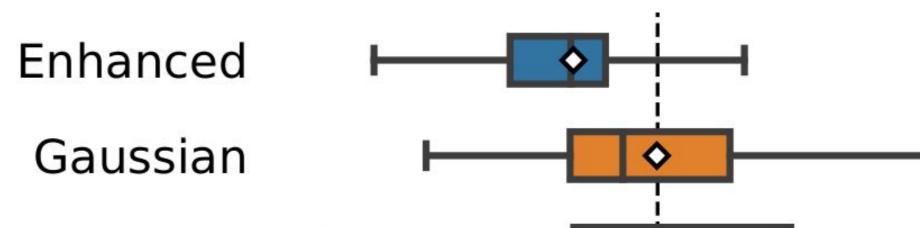
Explanations should overlap with manipulated areas. For better control, we recombine (real, fake) pairs and limit the forgery to a specific area. Then we can evaluate weakly-supervised manipulation detection.

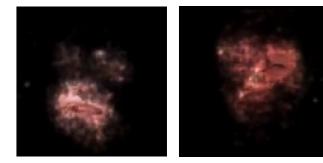
- Cutout augmentation results in better generalization from DFDC to DFD and better manipulation detection. Little effect on other metrics.
- Compared to the **CNN baseline**, the MViT **transformer** produces smoother and sparser explanations that also perform well for manipulation detection. Little effect on spatial locality.

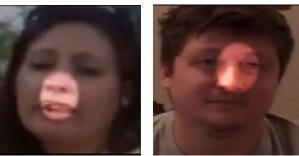
## **User presentation**

How to present a heatmap to users? Rare, medium, or well-done?

In a small study, users preferred the most structured visualizations (blob detection, semantic aggregation).

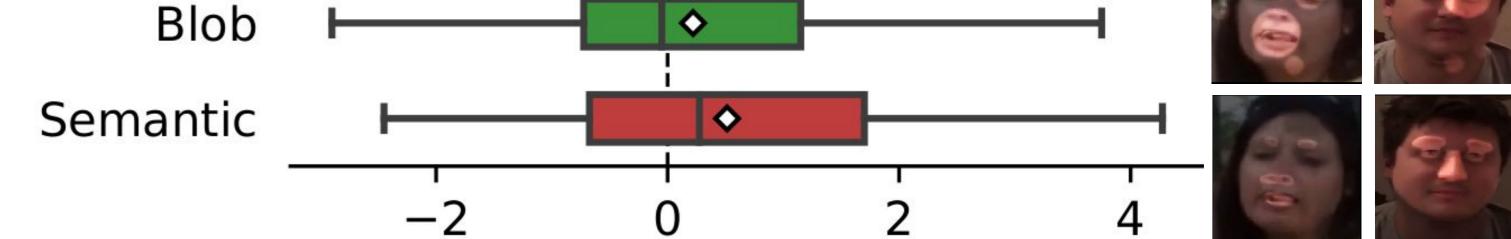








Two examples of part-specific manipulation:semantic parsing, real video, fake video



The post-processing techniques in our user study. From top to bottom: a simple blur filter to smoothen the heatmap, a single gaussian approximation, the largest blobs of relevance, an aggregation based on semantic face parsing,



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