

Fine-grained Few-shot Recognition by Deep Object Parsing

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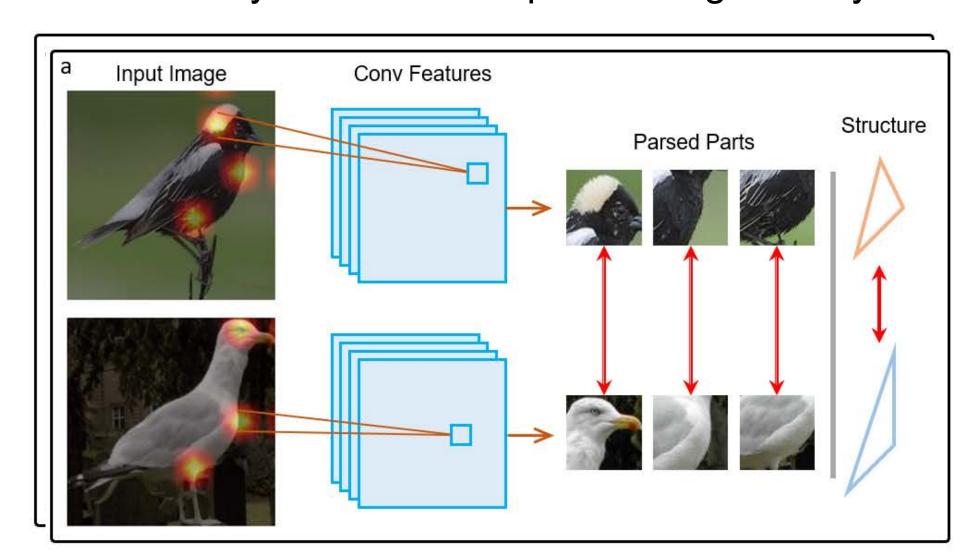


Motivation

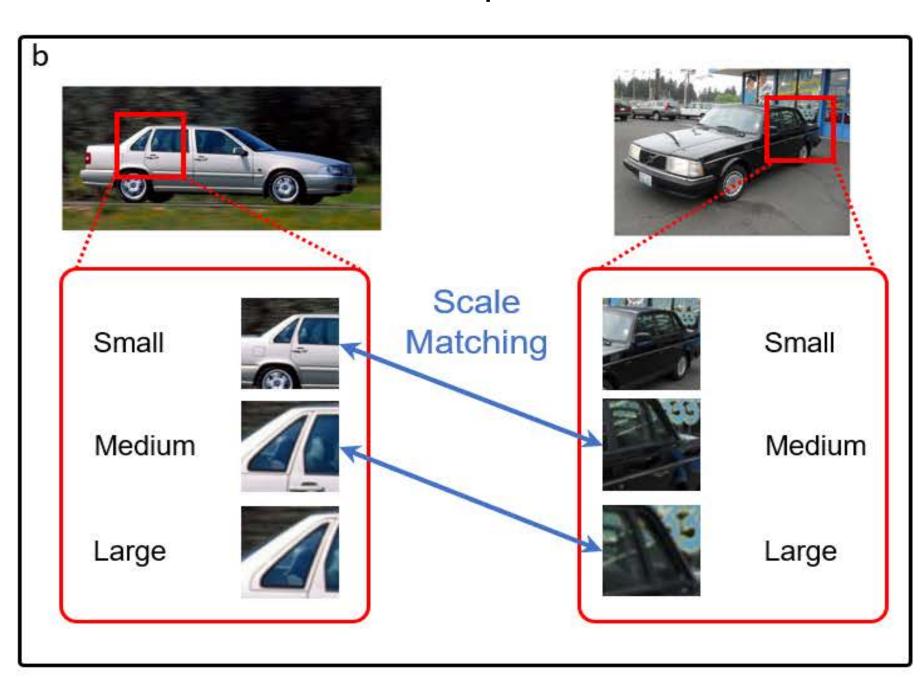
- > Salient parts and the geometry of the parts are important to good recognition accuracy.
- > Same part may be distorted or absent in the support samples due to the perspective and pose changes.

Our solution: Deep Object Parsing (DOP)

> DOP automatically learns salient parts and geometry.

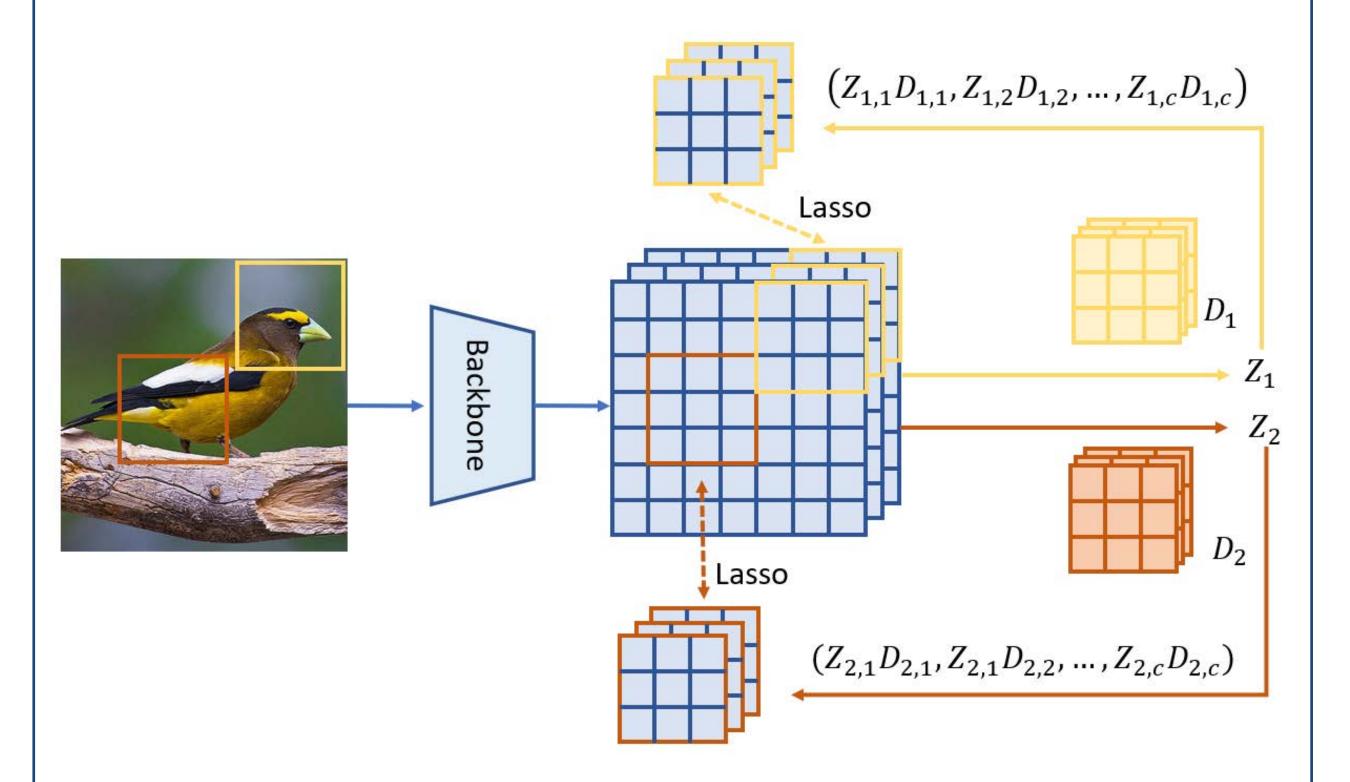


> DOP matches different scales of parts.



Method

A feature $\phi \in \mathbb{R}^{G \times G \times C}$ from instance x is parsed into K parts and Each part p is an $s \times s$ mask $M(\mu)$ around μ . Part is expressed coefficient $Z_{p,c}(\mu)$ of channel-wise templates $D_{p,c}$



Algorithm 1: Object Parsing using DNNs

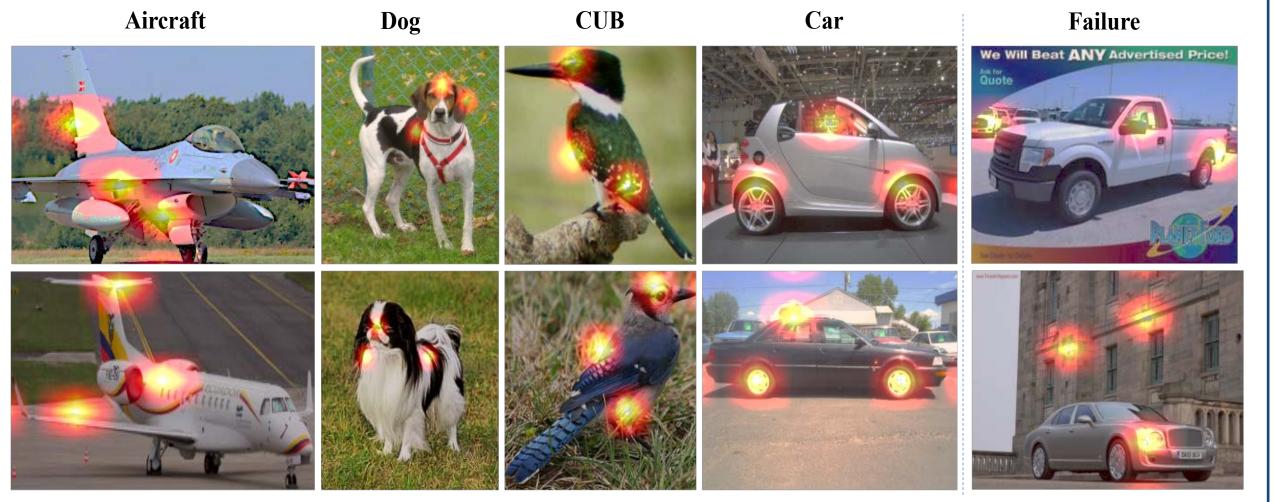
- 1 Input: image x
- 2 Parametric functions: convolutional backbone f, template collections \mathcal{D}_p
- **3** Get the convolutional feature $\phi = f(x)$
- 4 for $p \in [K]$ do
- 5 Estimate $\mu_p = \operatorname{argmax} \Pr_p(\mu \mid \phi; [\theta_{p,c}], [\lambda_c])$ by Eq. (4)
- 6 Compute $z'_{p,c}(\mu) = \frac{(D_{p,c} * \delta_{\mu}) \odot \phi_c(\mu)}{\|D_{p,c}\|^2}$
- 7 Thresholding: $z_{p,c}(\mu) = S_{\zeta}(z'_{p,c}(\mu))$
- 8 end for
- 9 Output: Part locations $[\mu_p]_{p\in[K]}$ and template coefficients $[z_{p,c}]_{p\in[K],c\in[C]}$
- Part expression as LASSO regression
- Part location estimation from optimal part expression
- > Few-shot recognition based on distances of features and geometry

Experiments

Methods	Backbones	CUB		Dog	
		1-shot	5-shot	1-shot	5-shot
VFD†[51]	ResNet12	79.12 ± 0.83	91.11±0.24	70.60±0.91	85.74±0.53
TOAN[19]	ResNet12	67.17 ± 0.81	82.09 ± 0.56	51.83 ± 0.80	69.83 ± 0.66
FRN[49]	ResNet12	83.16 ± 0.19	92.59 ± 0.23	62.07 ± 0.22	83.18 ± 0.14
TDM[23]	ResNet12	83.36 ± 0.22	92.08 ± 0.13	57.64 ± 0.22	75.77 ± 00.16
HelixFormer[55]	ResNet12	81.66 ± 0.30	91.83 ± 0.17	65.92 ± 0.49	80.65 ± 0.36
DOP	ResNet18	82.62±0.65	92.61±0.38	70.56±0.75	84.75±0.41
DOP	ResNet12	83.39 ± 0.82	93.01 ± 0.43	70.10 ± 0.79	85.12 ± 0.55

Methods	Backbones	Car		Aircraft	
		1-shot	5-shot	1-shot	5-shot
CTX[8]	ResNet12	55.66 ± 0.22	73.78 ± 0.16	65.53 ± 0.22	79.31 ± 0.13
TOAN[19]	ResNet12	76.62 ± 0.70	89.57 ± 0.40	= .0	= 6
FRN[49]	ResNet12	55.49 ± 0.21	74.54 ± 0.16	69.58 ± 0.22	82.98 ± 0.14
TDM[23]	ResNet12	68.36 ± 0.22	86.14 ± 0.13	70.89 ± 0.22	84.54 ± 0.16
HelixFormer[55]	ResNet12	79.40 ± 0.43	92.26 ± 0.15	74.01 ± 0.54	83.11 ± 0.41
DOP	ResNet18	81.41±0.71	93.48±0.38	83.26±0.24	92.41±0.45
DOP	ResNet12	81.83 ± 0.78	93.84 ± 0.45	84.50 ± 0.25	93.35 ± 0.48

Visualization of exemplar parts location learned by DOPM.



Visualization of re-weighting.



