

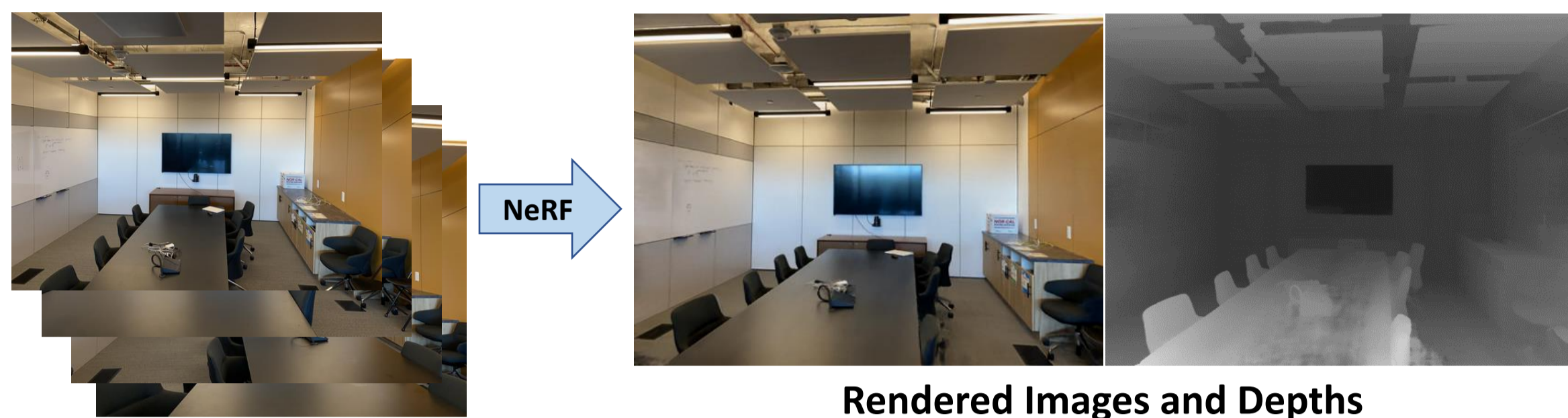
RoomNeRF: Representing Empty Room as Neural Radiance Fields for View Synthesis

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Motivation

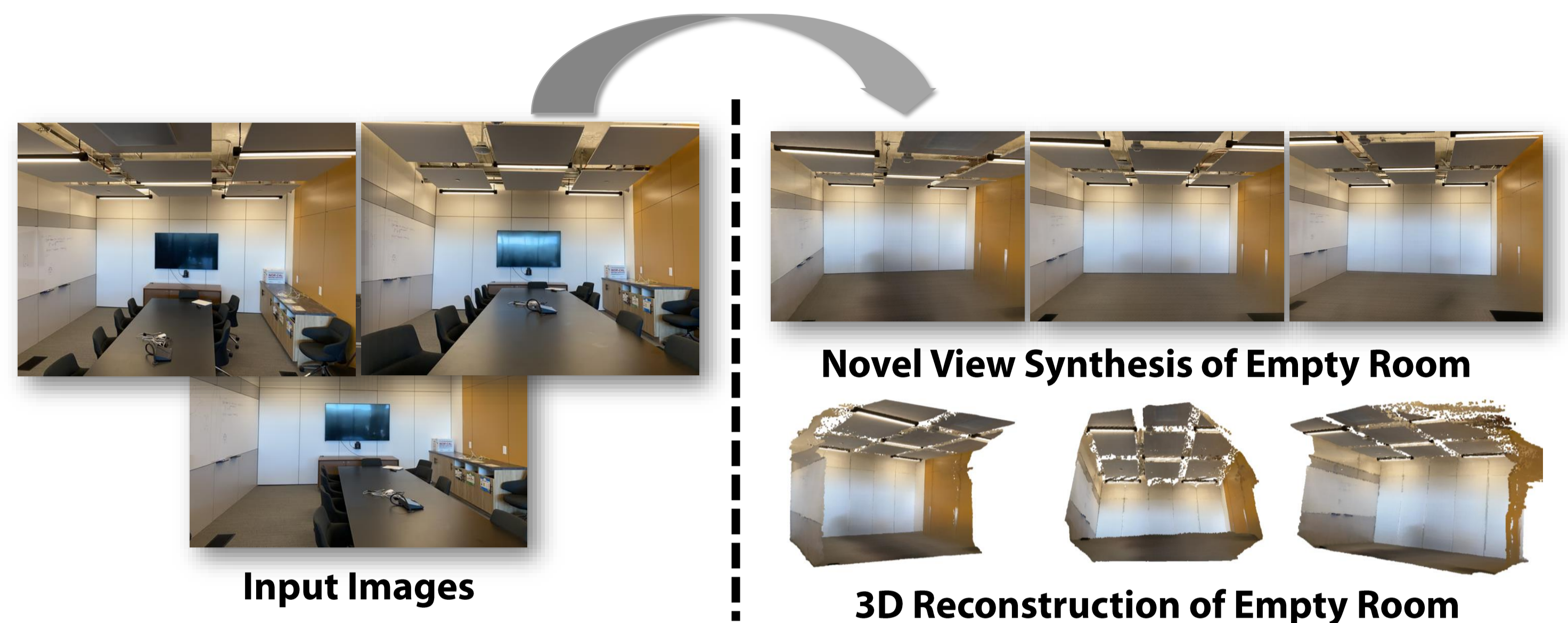
- One of the typical scenes to utilize NeRF is a **room**.
- The experience of being in a virtual room makes users curious about an empty room without furniture.



- **2D Inpainting techniques** are utilized to remove objects from room images.
- However, 2D inpainted images do not have **3D information**.
- The 3D information of an empty room can help NeRF to reconstruct a **visually and geometrically consistent** scene.

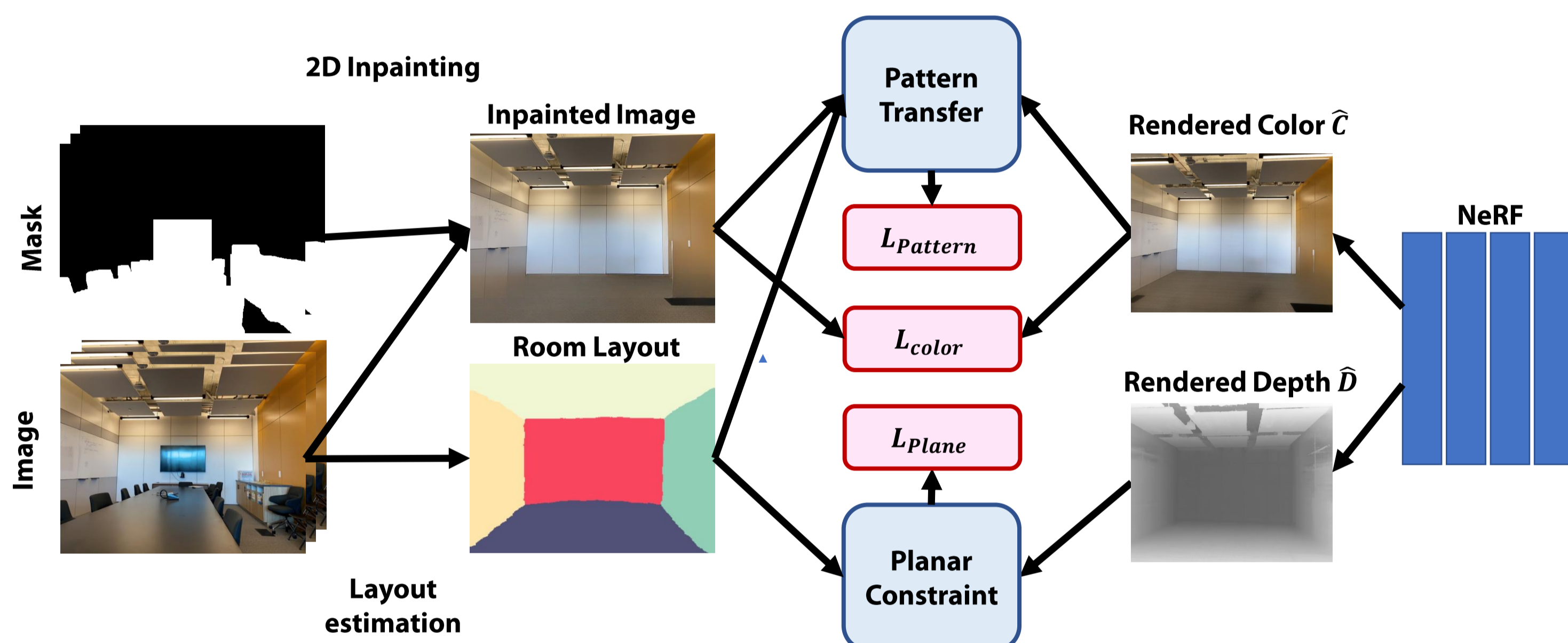
Problem

- Reconstructing **an empty room** with **the object-existing images**



Method

Overview



- Object masks, inpainted images, and room layouts are obtained in advance using Video object segmentation, 2D inpainting module, and layout estimation.
- Our Network exploits **the intrinsic properties of a room** shared by each plane
- Losses from Pattern transfer module and Planar Constraint Module help NeRF to reconstruct an empty room.

$$L_{PT} = \|M \odot \{\hat{R}_i - K_{j'}\}\|^2 \quad j' = \operatorname{argmax}_{j \in (M^c \cap L)} d(Q_i, K_j),$$

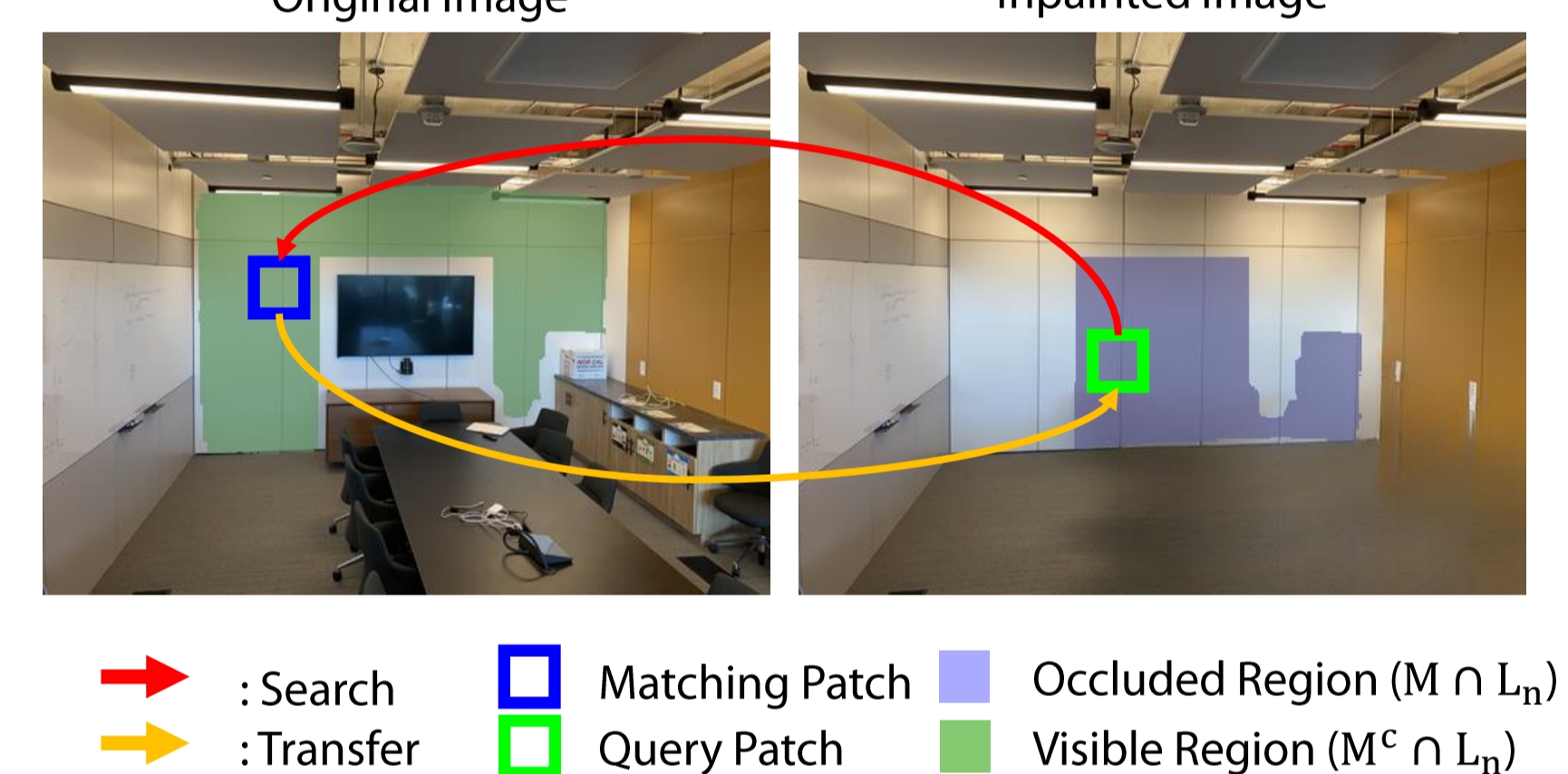
$$L_{PC} = \frac{1}{N_{Mask}} \sum_{n=1}^{N_{layout}} \sum_{D_n \in M \cap L_n} |\overrightarrow{A_n D_n} \times \overrightarrow{B_n D_n} \cdot \overrightarrow{C_n D_n}|$$

- Our total loss is as follows.

$$L_{total} = L_{color} + L_{depth} + \lambda_{PT} L_{PT} + \lambda_{PC} L_{PC}.$$

Pattern Transfer

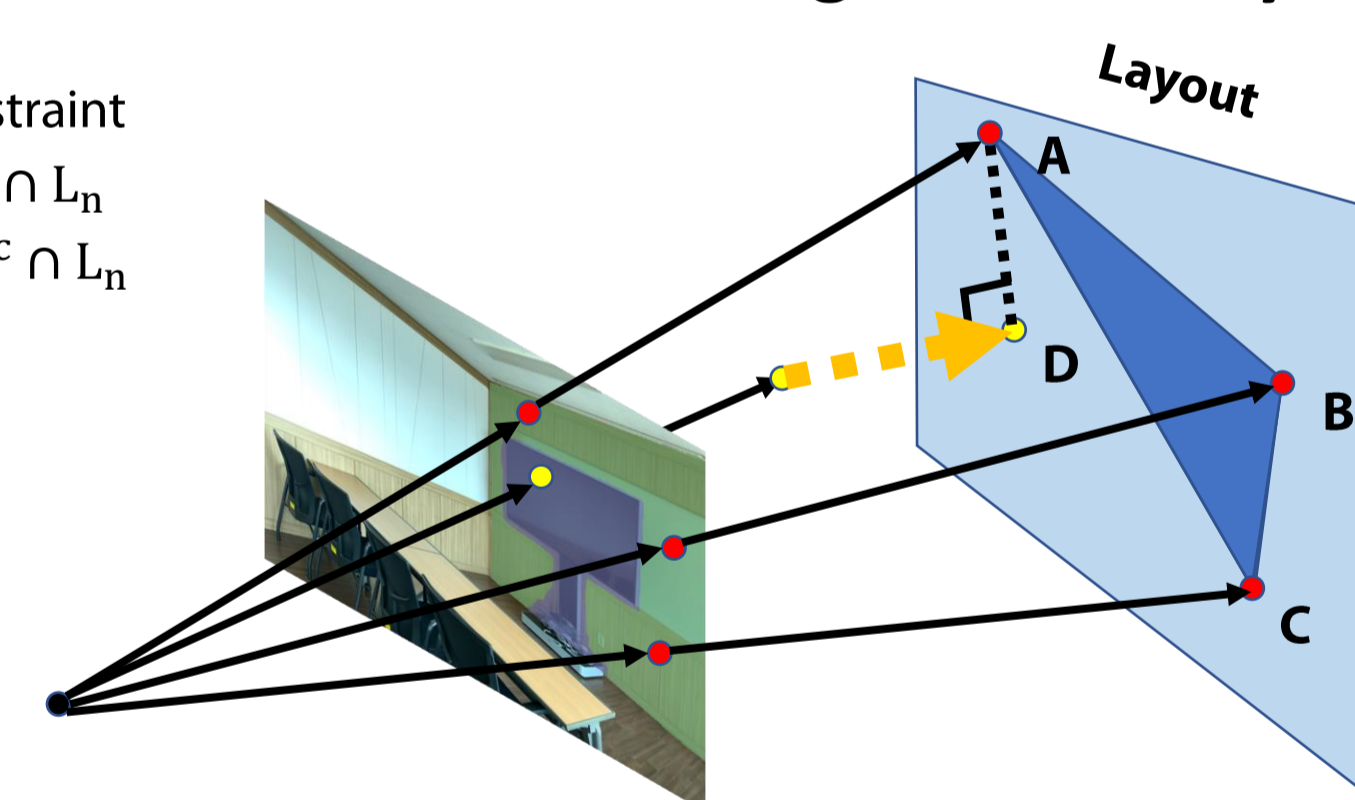
- All the walls in the room all have a certain pattern.
- To perform a **consistent visual reconstruction**, PT transfers the visual pattern of room wall to occluded regions.
- Two Step : **Search** the closest pattern from visible region and **Transfer** the pattern to occluded area.



Planar Constraint

- The Manhattan world assumes that all walls are flat.
- The occluded part of the wall should be **geometrically consistent** as a plane.

- : Planar constraint
- : Points $\in M \cap L_n$
- : Points $\in M^c \cap L_n$



Experimental Results

Quantitative Results

	Seminar room			Office room		
	PSNR(\uparrow)	SSIM(\uparrow)	LPIPS(\downarrow)	PSNR(\uparrow)	SSIM(\uparrow)	LPIPS(\downarrow)
Masked NeRF	21.69	0.8383	0.3781	20.61	0.9387	0.3409
Inpainted NeRF	23.44	0.8672	0.3722	21.07	0.9509	0.3199
NeRF-in [15]	23.35	0.8754	0.3420	21.42	0.8778	0.3310
Object-removal [31]	22.60	0.8591	0.3644	21.26	0.9425	0.3237
SPin-NeRF [20]	22.96	0.8643	0.2454	21.26	0.9467	0.2841
RoomNeRF (Ours)	23.82	0.9148	0.1546	21.58	0.9580	0.2434

Qualitative Results



Qualitative Results on LLFF and Replica dataset

